USBH device tree configuration

Stable: 24.09.2019 - 12:19 / Revision: 24.09.2019 - 12:18

Contents

1 Article purpose

This article explains how to configure the **USBH** internal peripheral when it is assigned to the Linux$^{®}$ OS. In that case, it is controlled by the USB framework.

The configuration is performed using the device tree mechanism.

It is used by *USBH Linux drivers* (EHCI[1], OHCI[2]) which register the relevant information in the USB framework.

2 DT bindings documentation

STM32 USBH internal peripheral is a USB Host device, composed of an **EHCI** controller and an **OHCI** controller.

Each controller is represented as a separate binding document:

- The generic USB EHCI controller device tree bindings[3] document deals with standard EHCI controller core resources (e.g. registers, clock, reset, interrupt, ...).
- The generic USB OHCI controller device tree bindings[4] document deals with standard OHCI controller core resources (e.g. registers, clock, reset, interrupt, ...).

Each controller uses the generic USB Host Controller Device (HCD) properties and generic USB properties, proposed by USB framework:

- The generic USB HCD device tree bindings[5] document deals with USB Host Controller PHY resources.
- The generic USB device tree bindings[6] document deals with USB optional properties (e.g. maximum speed, companion, ...).

3 DT configuration

This hardware description is a combination of the **STM32 microprocessor** device tree files (*.dtsi* extension) and **board** device tree files (*.dts* extension). See the Device tree for an explanation of the device tree file split.

STM32CubeMX can be used to generate the board device tree. Refer to How to configure the DT using STM32CubeMX for more details.

3.1 DT configuration (STM32 level)

The **usbh_ehci** and **usbh_ohci** DT nodes are declared in stm32mp157c.dtsi[7].

They are composed of a set of properties, used to describe the USBH_EHCI and USBH_OHCI controllers: registers address, clocks, resets, interrupts...

```
usbh_ohci: usbh-ohci@5800c000 {                       /* USBH OHCI controller */
        compatible = "generic-ohci";
        reg = <0x5800c000 0x1000>;
        clocks = <&rcc USBH>;
        resets = <&rcc USBH_R>;
        interrupts = <GIC_SPI 74 IRQ_TYPE_LEVEL_HIGH>;
        status = "disabled";
};

usbh_ehci: usbh-ehci@5800d000 {                       /* USBH EHCI controller */
        compatible = "generic-ehci";
        reg = <0x5800d000 0x1000>;
        clocks = <&rcc USBH>;
        resets = <&rcc USBH_R>;
        interrupts = <GIC_SPI 75 IRQ_TYPE_LEVEL_HIGH>;
        companion = <&usbh_ohci>;                      /* When USBH EHCI controller detect
        status = "disabled";                            * that port is switched over to t
};
```

⚠️ **This device tree part is related to STM32 microprocessors. It must be kept as is, without being modified by the end-user.**

3.2 DT configuration (board level)

Follow the sequences described in the below chapters to configure and enable the USBH on your board.

USBH supports up to two physical ports, using on-chip USBPHYC:

- USBPHYC port#1 is assigned to the USBH
- USBPHYC port#2 can be statically assigned to the USBH or to the OTG

> Please refer to USBPHYC device tree configuration for additional information on the USBPHYC configuration

USBH is composed of EHCI and OHCI controllers:

- high-speed operation is achieved through the EHCI controller
- full-speed and low-speed operation can be achieved by either:
    - a high-speed HUB IC wired to the downstream port
    - the OHCI controller

3.2.1 DT configuration with external high speed-HUB

- Enable the **usbh_ehci** by setting **status = "okay"**
- Configure the PHY(s) through **phys** and **phy-names**

> There's no need to enable **usbh_ohci**, when all the low-speed and full-speed traffic is managed by the high-speed hub directly connected to the downstream port.

3.2.2 DT configuration with OHCI to achieve full-speed and low-speed

- Enable the **usbh_ehci** by setting **status = "okay"**
- Enable the **usbh_ohci** by setting **status = "okay"**

For both controllers:

- Configure the PHY(s) through **phys** and **phy-names**

3.3 DT configuration examples

3.3.1 DT configuration when using port0 with a high-speed hub

Below example shows how to configure the USBH when using the physical port 0 (the second physical port is unused).

A high-speed hub controller IC is used on the board: no need to enable usbh_ohci, all low-speed and full-speed traffic is managed by the hub.

```
&usbh_ehci {
        phys = Template:LightBlue;              Template:LightBlue
        phy-names = "usb";
        status = "okay";
};

Template:LightBlue
```

3.3.2 DT configuration when using port0

Below example shows how to configure the USBH when using the physical port 0 (the second physical port is unused, or in use by the OTG and no high-speed hub is used).

```
&usbh_ehci {
        phys = Template:LightBlue;              Template:LightBlue
        phy-names = "usb";
        status = "okay";
};

&usbh_ohci {
        phys = Template:LightBlue;              Template:LightBlue
        phy-names = "usb";
        status = "okay";
};
```

3.3.3 DT configuration when using the two physical ports

Below example shows how to configure the USBH when using the two physical ports.

```
&usbh_ehci {
        phys = Template:LightBlue, Template:Rose;       Template:LightBlue
                                                        Template:Rose
        phy-names = "usb", "usb";
        status = "okay";
};
&usbh_ohci {
        phys = Template:LightBlue, Template:Rose;       Template:LightBlue
                                                        Template:Rose
        phy-names = "usb", "usb";
        status = "okay";
};
```

4 How to configure the DT using STM32CubeMX

The STM32CubeMX tool can be used to configure the STM32MPU device and get the corresponding platform configuration device tree files.
The STM32CubeMX may not support all the properties described in the above DT bindings documentation paragraph. If so, the tool inserts **user sections** in the generated device tree. These sections can then be edited to add some properties and they are preserved from one generation to another. Refer to STM32CubeMX user manual for further information.

5 References

Please refer to the following links for full description:

1. ↑ drivers/usb/host/ehci-platform.c , Generic platform ehci driver
2. ↑ drivers/usb/host/ohci-platform.c , Generic platform ohci driver
3. ↑ Documentation/devicetree/bindings/usb/usb-ehci.txt Generic USB EHCI controller device tree bindings

4. ↑ Documentation/devicetree/bindings/usb/usb-ohci.txt Generic USB OHCI controller device tree bindings
5. ↑ Documentation/devicetree/bindings/usb/usb-hcd.txt Generic USB HCD (Host Controller Device) device tree bindings
6. ↑ [6.06.1] Documentation/devicetree/bindings/usb/generic.txt Generic USB device tree bindings
7. ↑ arch/arm/boot/dts/stm32mp157c.dtsi , STM32MP157C device tree file

Operating System

USB Host (STM32 specific)

Enhanced Host Controller Interface

Open Host Controller Interface

Device Tree

Generic Interrupt Controller

Serial Peripheral Interface