



STM32CubeMP1 architecture



Contents

1. STM32CubeMP1 architecture	123
2. Coprocessor management overview	15
3. Device tree	27
4. Getting started with STM32 MPU devices	39
5. Linux RPMsg framework overview	51
6. Linux application frameworks overview	63
7. Resource manager for coprocessing	75
8. STM32CubeIDE	87
9. STM32CubeMP1 Package	99
10. STM32CubeMP1 Package release note	111
11. STM32MP15 device tree	135
12. STM32MP15 peripherals overview	147
13. STM32MP15 resources	159



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Contents

1 Introduction	124
2 STM32Cube MP1 Package architecture	125
2.1 Level 0 (Drivers)	126
2.1.1 HAL drivers	126
2.1.1.1 HAL drivers overview	126
2.1.1.2 List of HAL drivers	126
2.1.2 LL drivers	127
2.1.2.1 Low Layer drivers overview	127
2.1.2.2 List of LL drivers	128
2.1.3 BSP drivers	128
2.1.3.1 BSP drivers overview	128
2.1.3.2 List of BSP drivers	128
2.2 Level 1 (Middlewares)	129
2.2.1 OpenAMP	129
2.2.2 FreeRTOS	129
2.3 Level 2 (Boards demonstrations)	130
2.4 Utilities	130
2.5 CMSIS	131
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	134
4 References	135



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

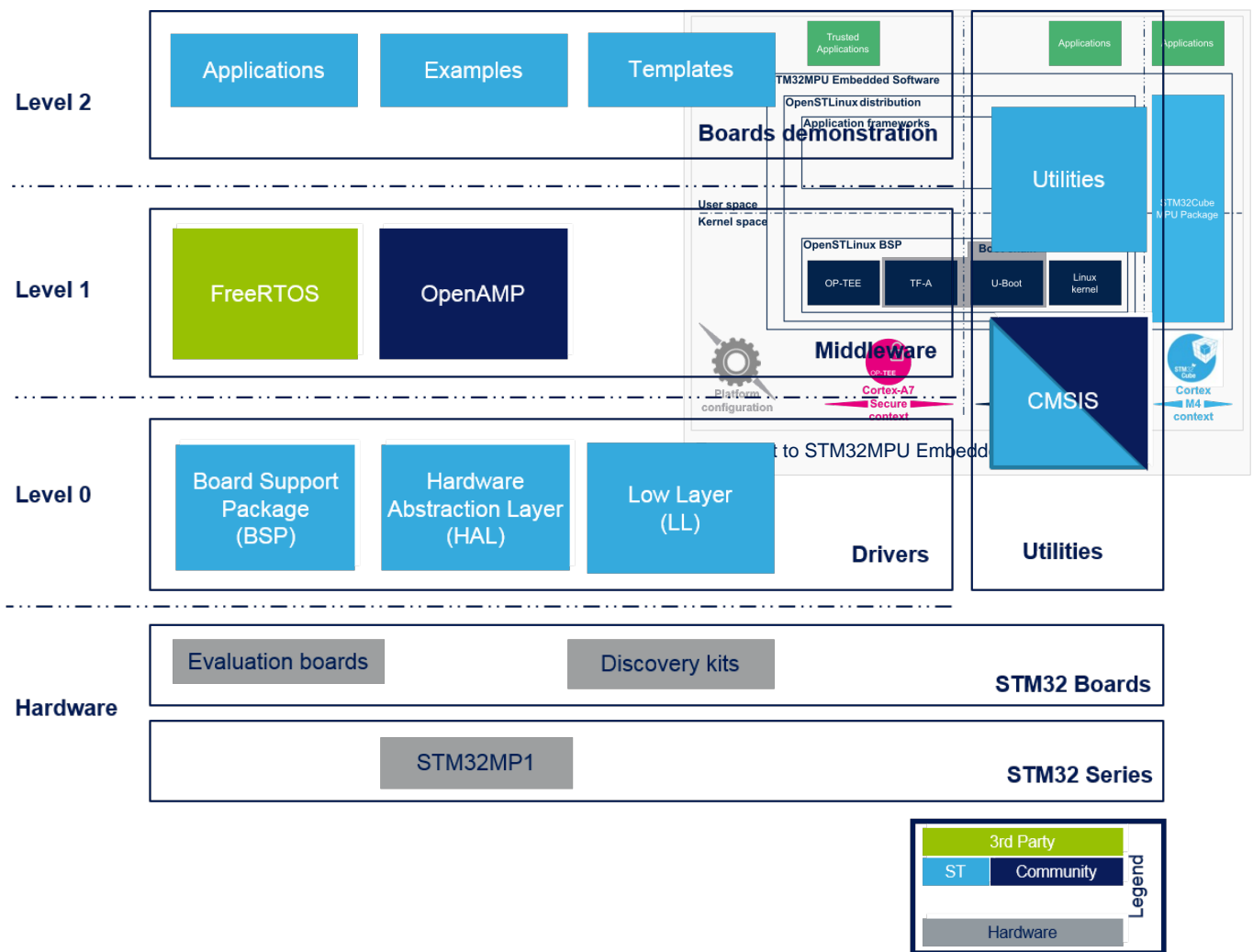
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

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- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

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— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
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stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
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stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
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stm32mp1xx_hal_hash.c	HASH HAL Driver
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stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

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stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
├── stm32mp15xx_disco_bus.c
├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory footprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

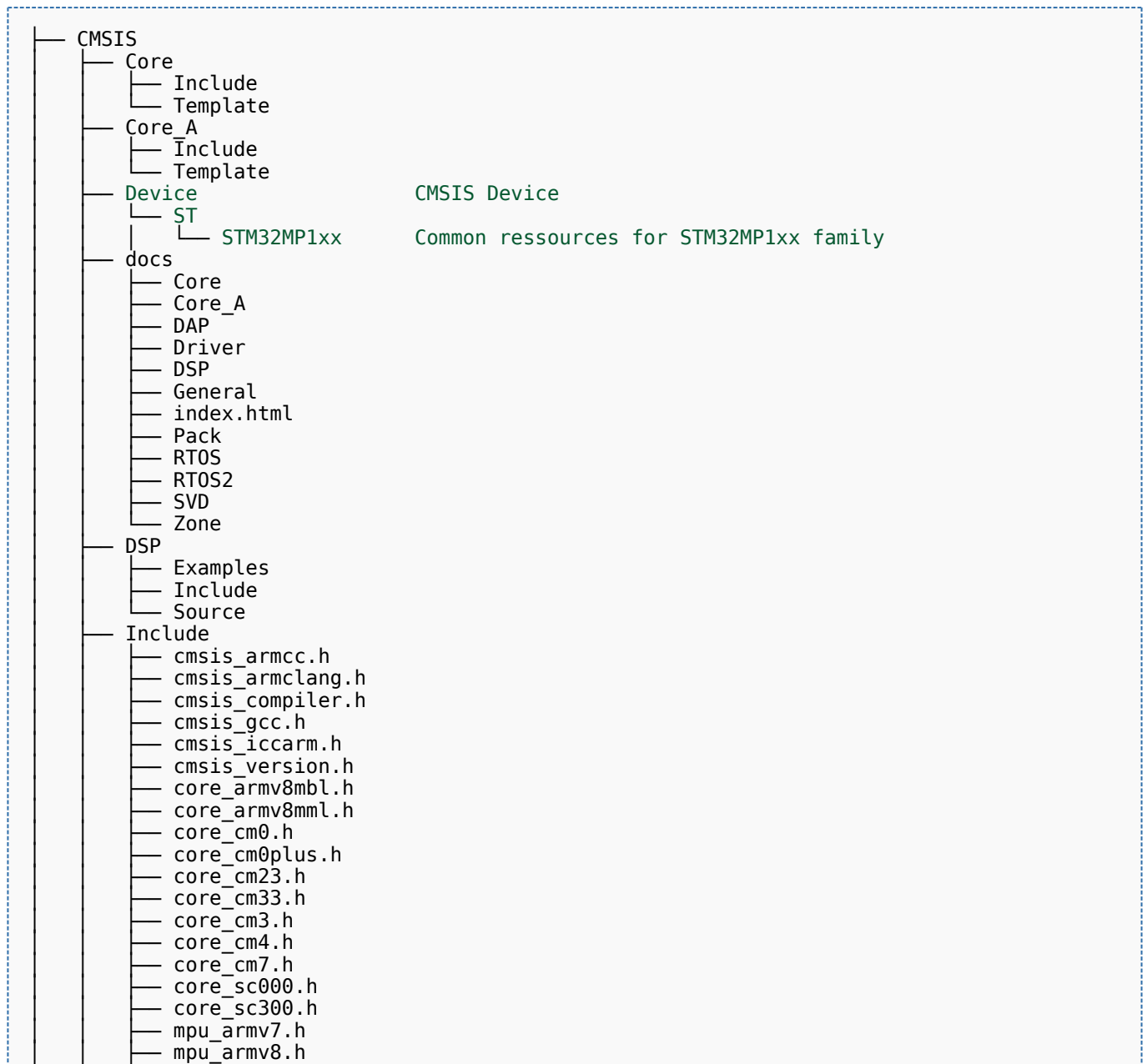
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





```
resources available | | | — startup_stm32mp153c_cm4.s --> Added to fit with the
resources available | | | — startup_stm32mp157a_cm4.s --> Added to fit with the
resources available | | | — startup_stm32mp157c_cm4.s --> Added to fit with the
resources available | | | — linker linker files and startup
files (memory mapping) | — iar
                        | — linker
                        |   — stm32mp15xx_sram.icf
                        | — startup_stm32mp15xx.s
                        | — system_stm32mp1xx.c
```

Information

Notes:

- Several **CMSIS devices** are provided for a same family (ex: stm32mp157cxx.h & stm32mp157axx.h are provided for stm32mp1 family). It is done to fit exactly the resources present in the STM32 Part Number (ex: stm32mp157a does not include CRYIP peripheral).
- Usage of the right **CMSIS device** is done thanks to a preprocessor switch in IDE project settings (ex: STM32MP157Axx, or STM32MP157Cxx, or STM32MP157Dxx, or STM32MP157Fxx)



3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
 - All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
 - Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	16
2 STM32Cube MP1 Package architecture	17
2.1 Level 0 (Drivers)	18
2.1.1 HAL drivers	18
2.1.1.1 HAL drivers overview	18
2.1.1.2 List of HAL drivers	18
2.1.2 LL drivers	19
2.1.2.1 Low Layer drivers overview	19
2.1.2.2 List of LL drivers	20
2.1.3 BSP drivers	20
2.1.3.1 BSP drivers overview	20
2.1.3.2 List of BSP drivers	20
2.2 Level 1 (Middlewares)	21
2.2.1 OpenAMP	21
2.2.2 FreeRTOS	21
2.3 Level 2 (Boards demonstrations)	22
2.4 Utilities	22
2.5 CMSIS	23
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	26
4 References	27



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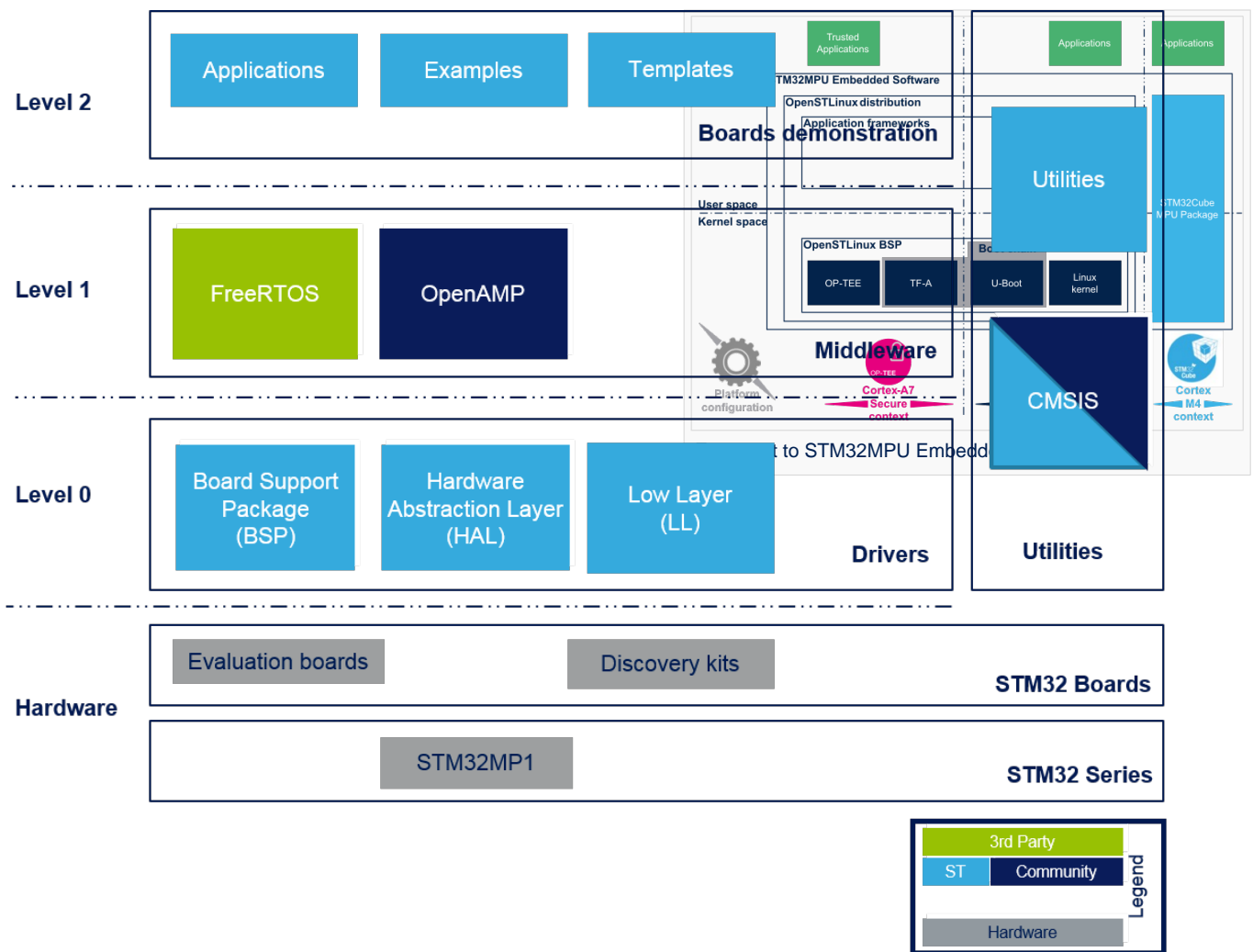
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2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



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- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

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stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
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├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
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├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
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    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Reso
  urce_manager_for_coprocessing
```



2.5 CMSIS

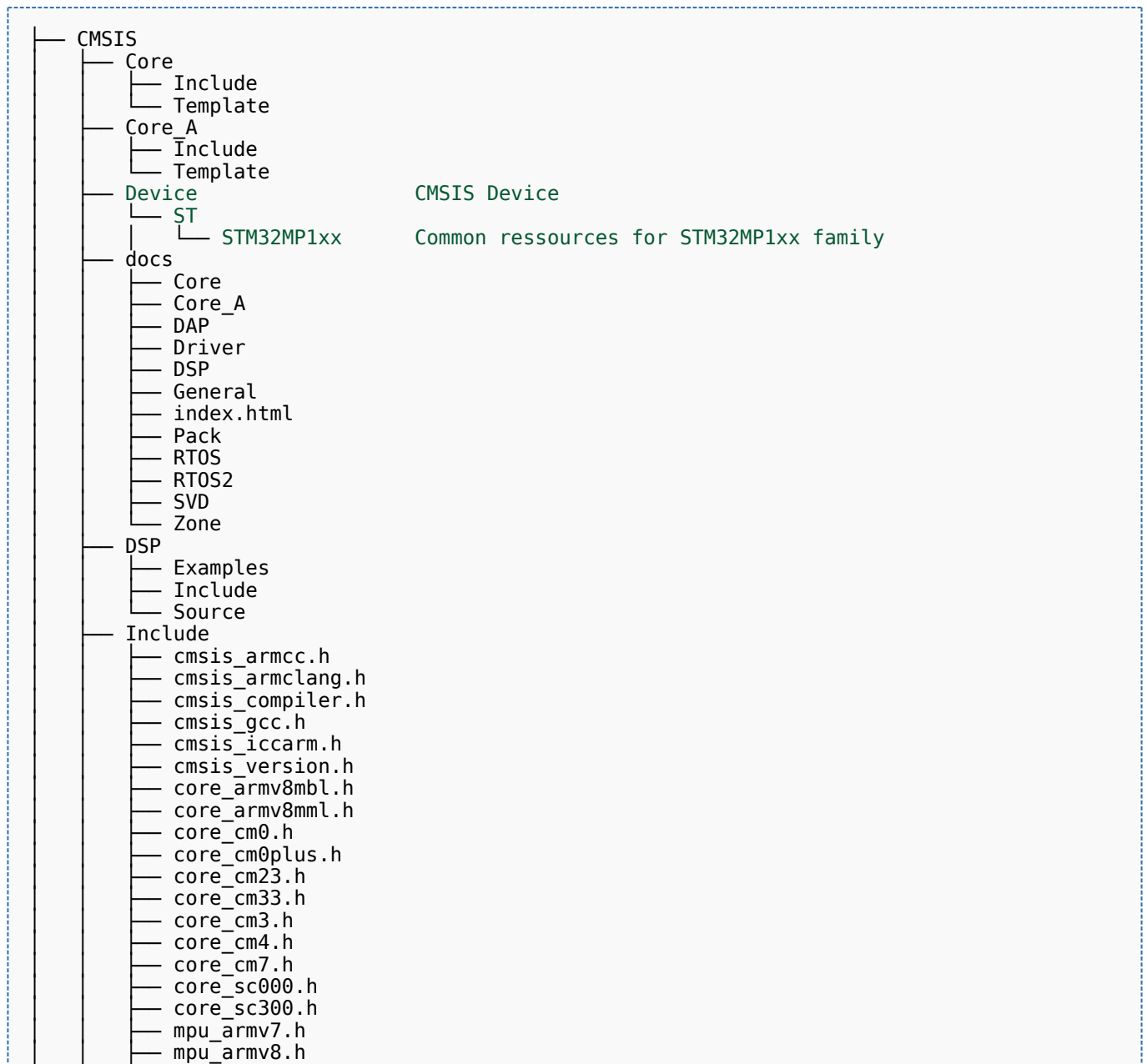
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

- The middleware and BSP components offered is smaller in **STM32Cube MP1 Package** as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
 - All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
 - Specific pieces of software have been added to handle multi-core operations:
 - [OpenAMP](#) middleware for Intercommunication processor between cortex A and cortex M (RPMsg protocol implementation)
 - [Resource Manager](#) library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load **STM32Cube MPU** firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	28
2 STM32Cube MP1 Package architecture	29
2.1 Level 0 (Drivers)	30
2.1.1 HAL drivers	30
2.1.1.1 HAL drivers overview	30
2.1.1.2 List of HAL drivers	30
2.1.2 LL drivers	31
2.1.2.1 Low Layer drivers overview	31
2.1.2.2 List of LL drivers	32
2.1.3 BSP drivers	32
2.1.3.1 BSP drivers overview	32
2.1.3.2 List of BSP drivers	32
2.2 Level 1 (Middlewares)	33
2.2.1 OpenAMP	33
2.2.2 FreeRTOS	33
2.3 Level 2 (Boards demonstrations)	34
2.4 Utilities	34
2.5 CMSIS	35
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	38
4 References	39



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

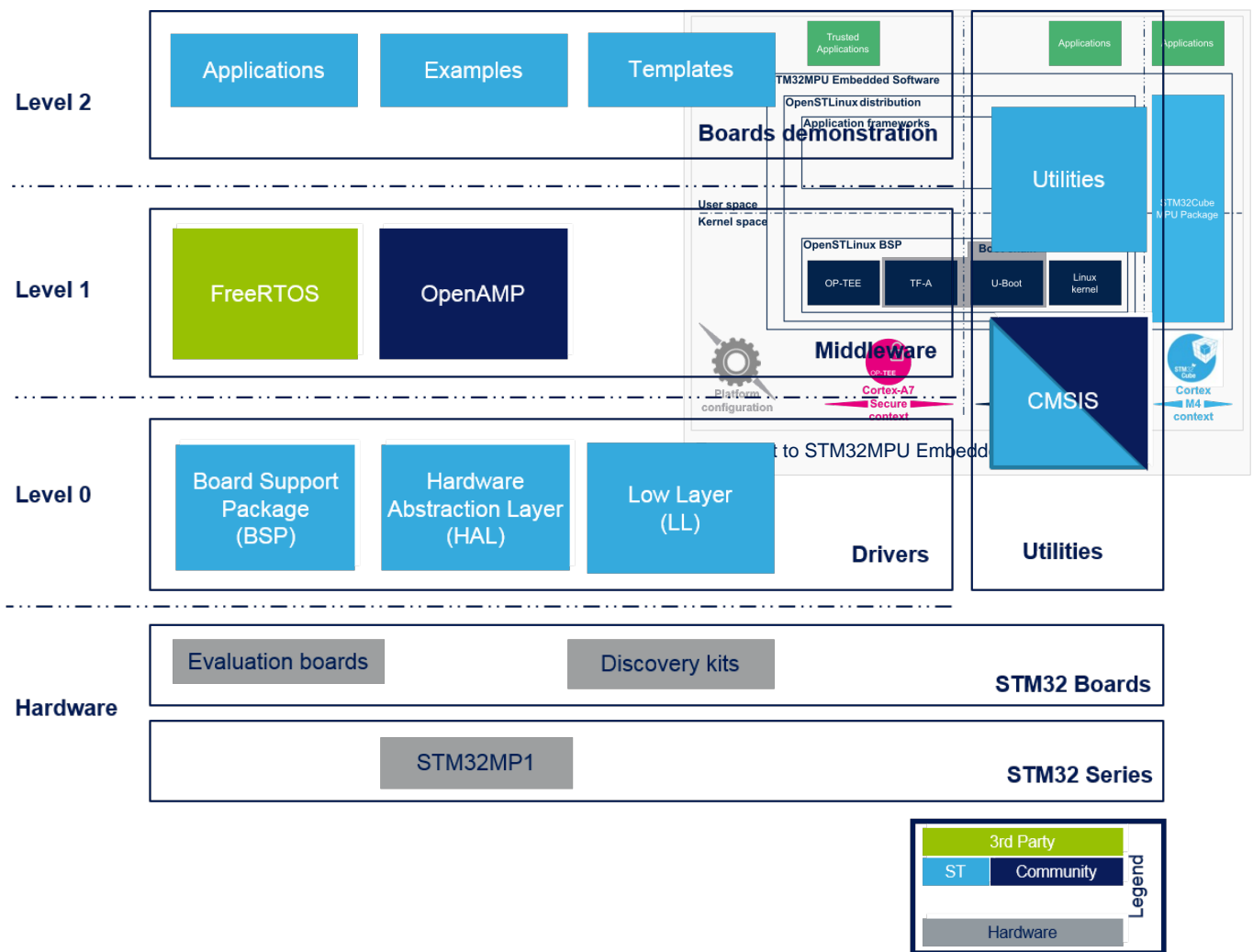
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
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stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
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2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

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The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
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The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

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    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

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FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

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- Multithread management
- Pre-emptive scheduling
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- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

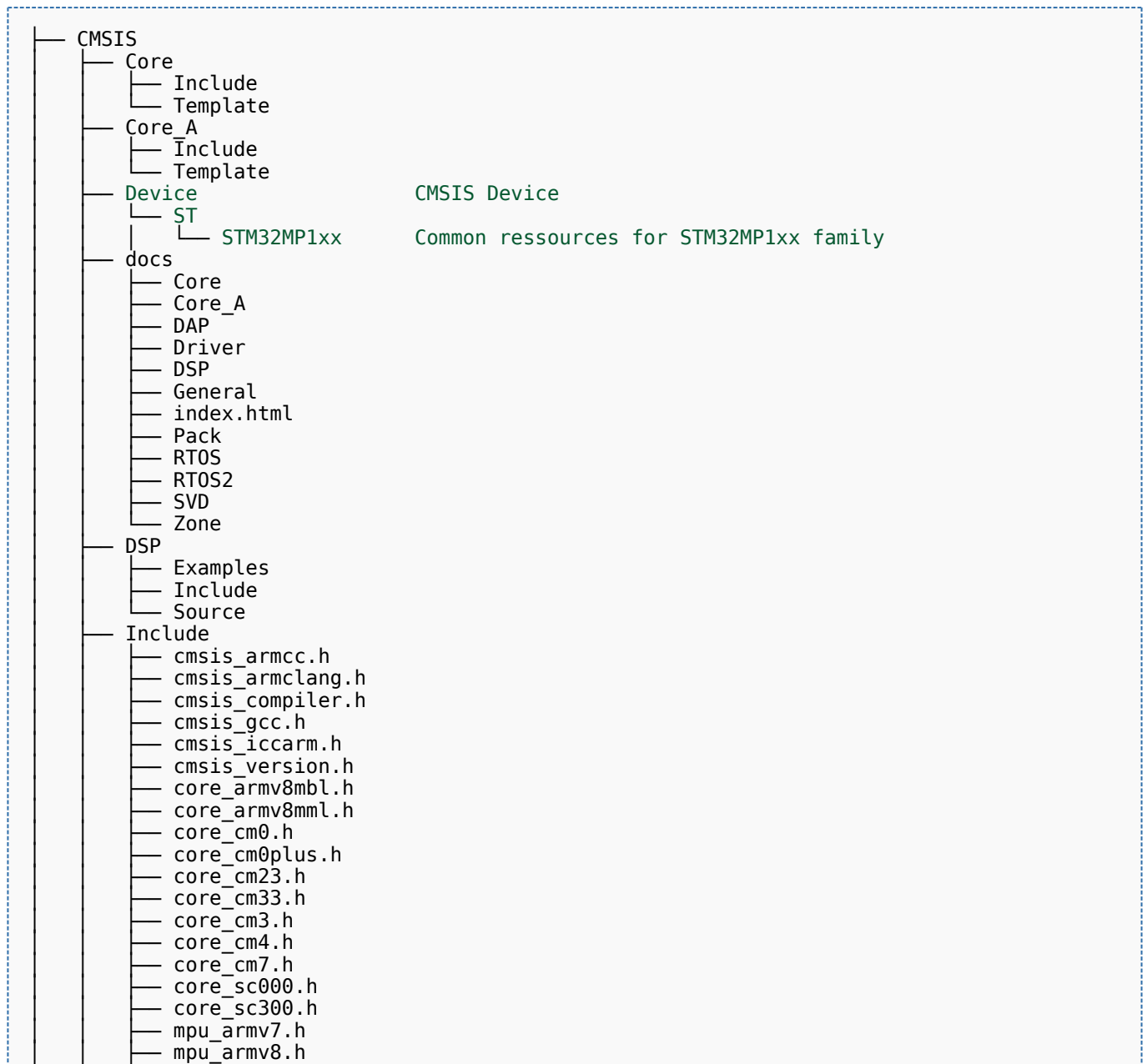
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

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The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	40
2 STM32Cube MP1 Package architecture	41
2.1 Level 0 (Drivers)	42
2.1.1 HAL drivers	42
2.1.1.1 HAL drivers overview	42
2.1.1.2 List of HAL drivers	42
2.1.2 LL drivers	43
2.1.2.1 Low Layer drivers overview	43
2.1.2.2 List of LL drivers	44
2.1.3 BSP drivers	44
2.1.3.1 BSP drivers overview	44
2.1.3.2 List of BSP drivers	44
2.2 Level 1 (Middlewares)	45
2.2.1 OpenAMP	45
2.2.2 FreeRTOS	45
2.3 Level 2 (Boards demonstrations)	46
2.4 Utilities	46
2.5 CMSIS	47
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	50
4 References	51



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

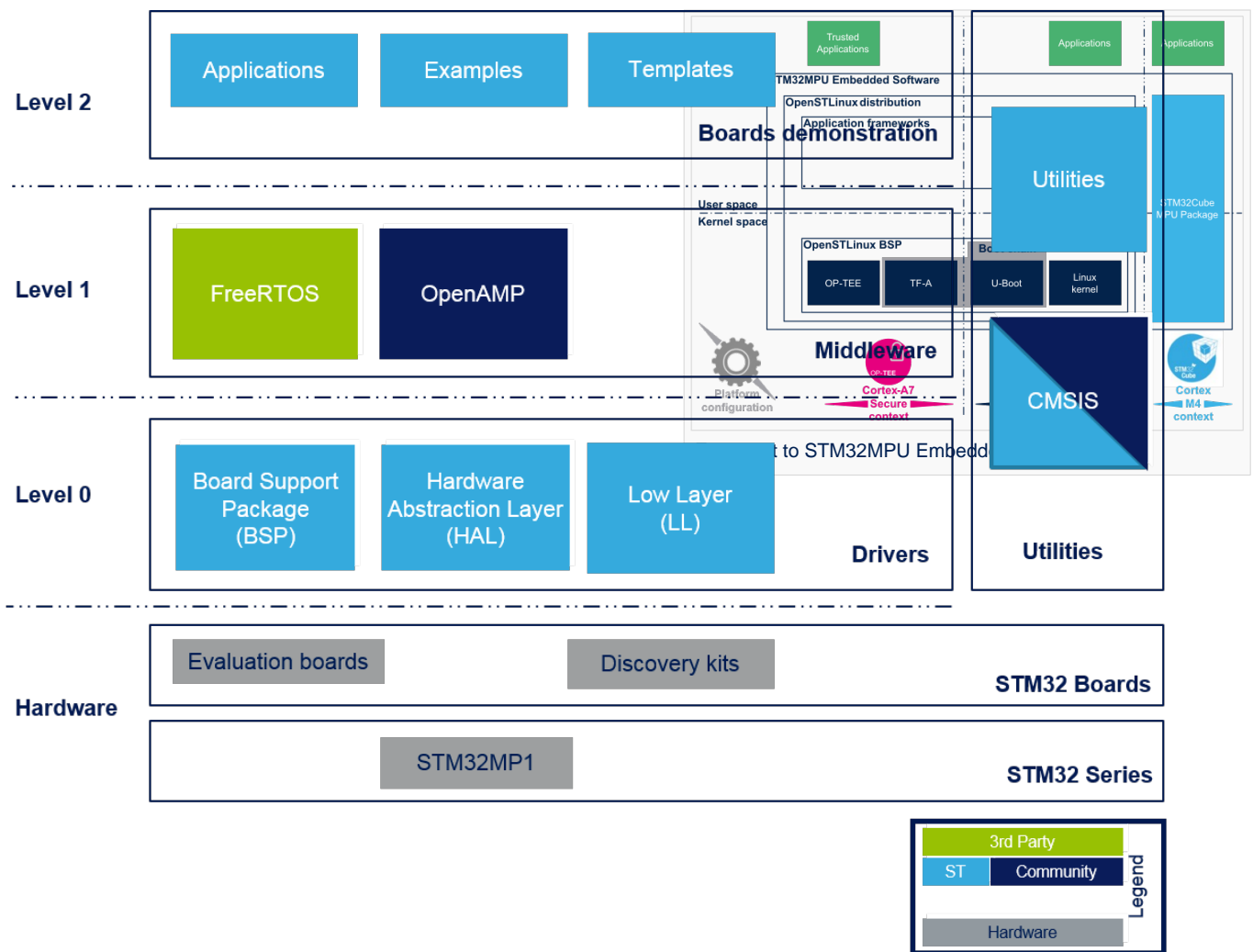
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



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stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
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stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
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├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

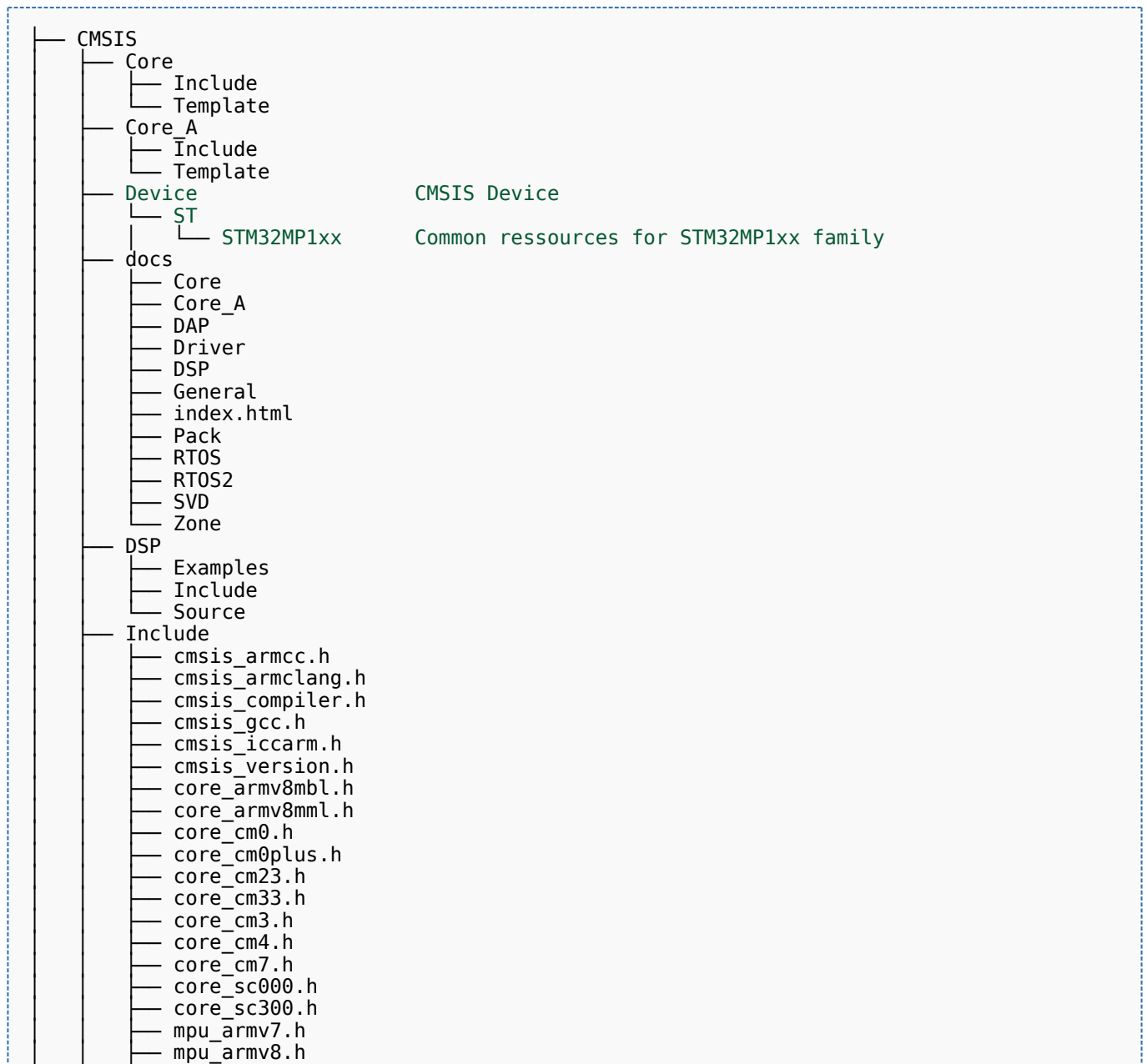
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	52
2 STM32Cube MP1 Package architecture	53
2.1 Level 0 (Drivers)	54
2.1.1 HAL drivers	54
2.1.1.1 HAL drivers overview	54
2.1.1.2 List of HAL drivers	54
2.1.2 LL drivers	55
2.1.2.1 Low Layer drivers overview	55
2.1.2.2 List of LL drivers	56
2.1.3 BSP drivers	56
2.1.3.1 BSP drivers overview	56
2.1.3.2 List of BSP drivers	56
2.2 Level 1 (Middlewares)	57
2.2.1 OpenAMP	57
2.2.2 FreeRTOS	57
2.3 Level 2 (Boards demonstrations)	58
2.4 Utilities	58
2.5 CMSIS	59
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	62
4 References	63



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

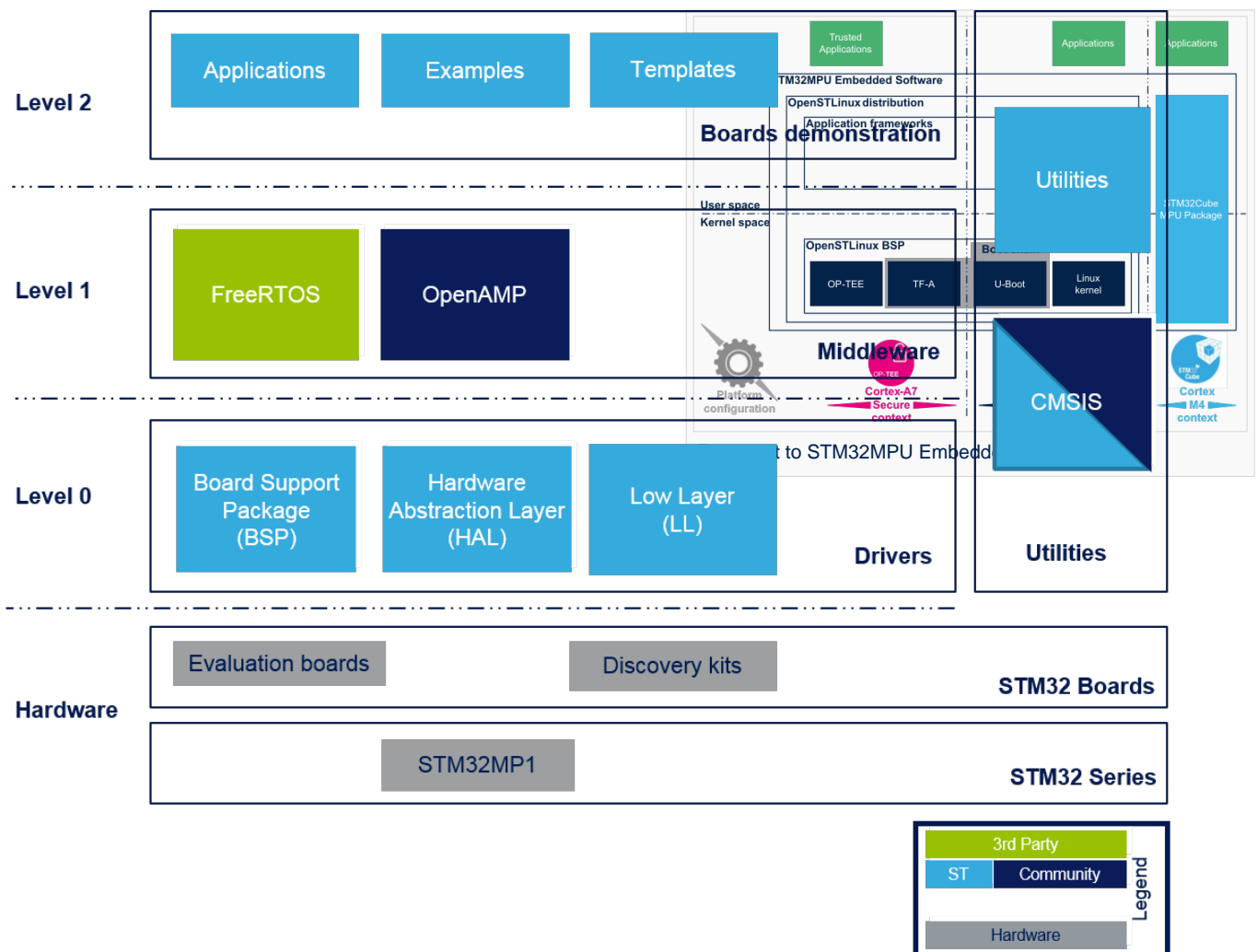
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

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2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
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2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

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The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

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The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

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2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



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    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h

```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory footprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

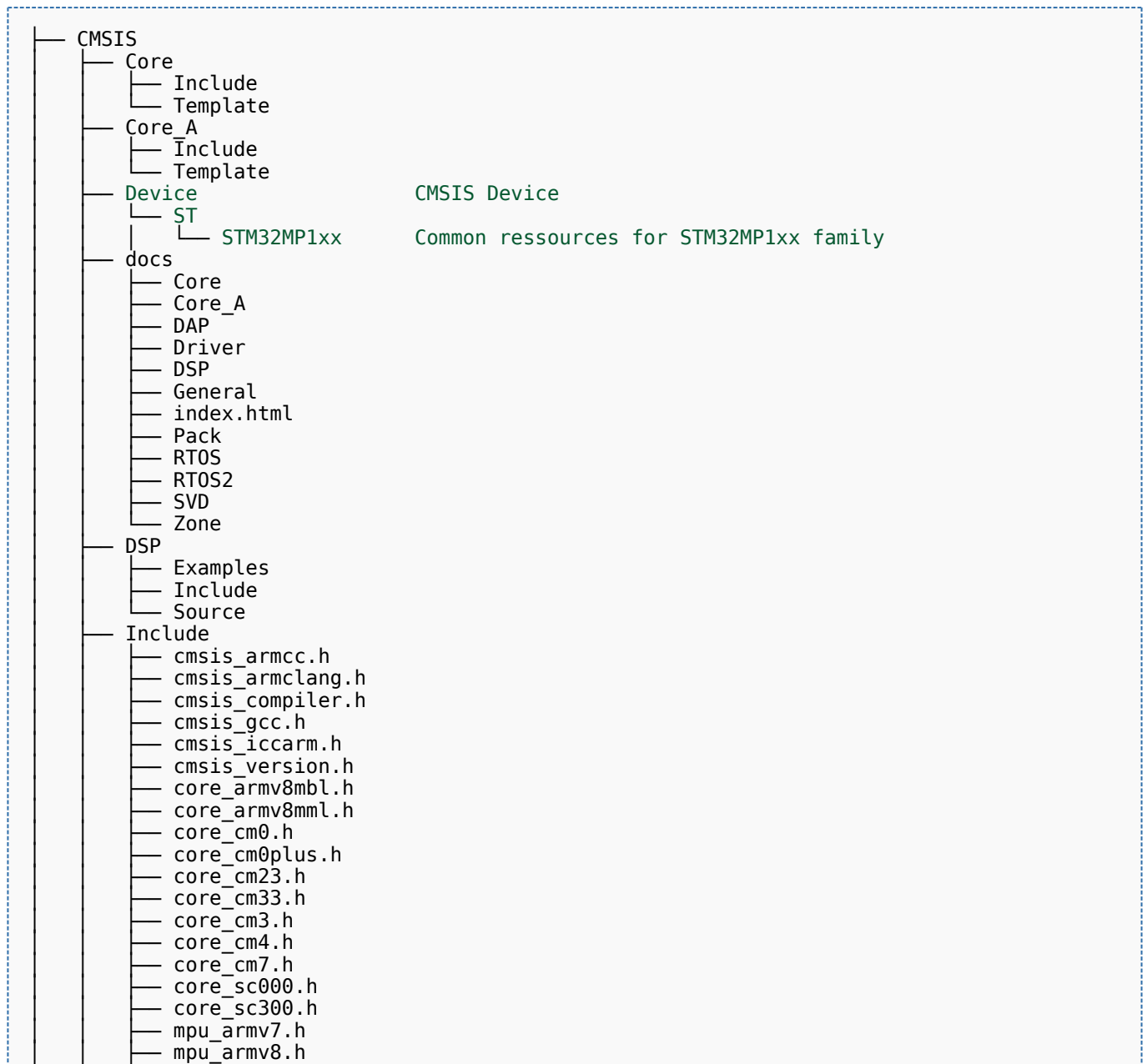
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

- The middleware and BSP components offer is smaller in **STM32Cube MP1 Package** as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
- All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - [OpenAMP](#) middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - [Resource Manager](#) library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load **STM32Cube MPU** firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	64
2 STM32Cube MP1 Package architecture	65
2.1 Level 0 (Drivers)	66
2.1.1 HAL drivers	66
2.1.1.1 HAL drivers overview	66
2.1.1.2 List of HAL drivers	66
2.1.2 LL drivers	67
2.1.2.1 Low Layer drivers overview	67
2.1.2.2 List of LL drivers	68
2.1.3 BSP drivers	68
2.1.3.1 BSP drivers overview	68
2.1.3.2 List of BSP drivers	68
2.2 Level 1 (Middlewares)	69
2.2.1 OpenAMP	69
2.2.2 FreeRTOS	69
2.3 Level 2 (Boards demonstrations)	70
2.4 Utilities	70
2.5 CMSIS	71
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	74
4 References	75



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

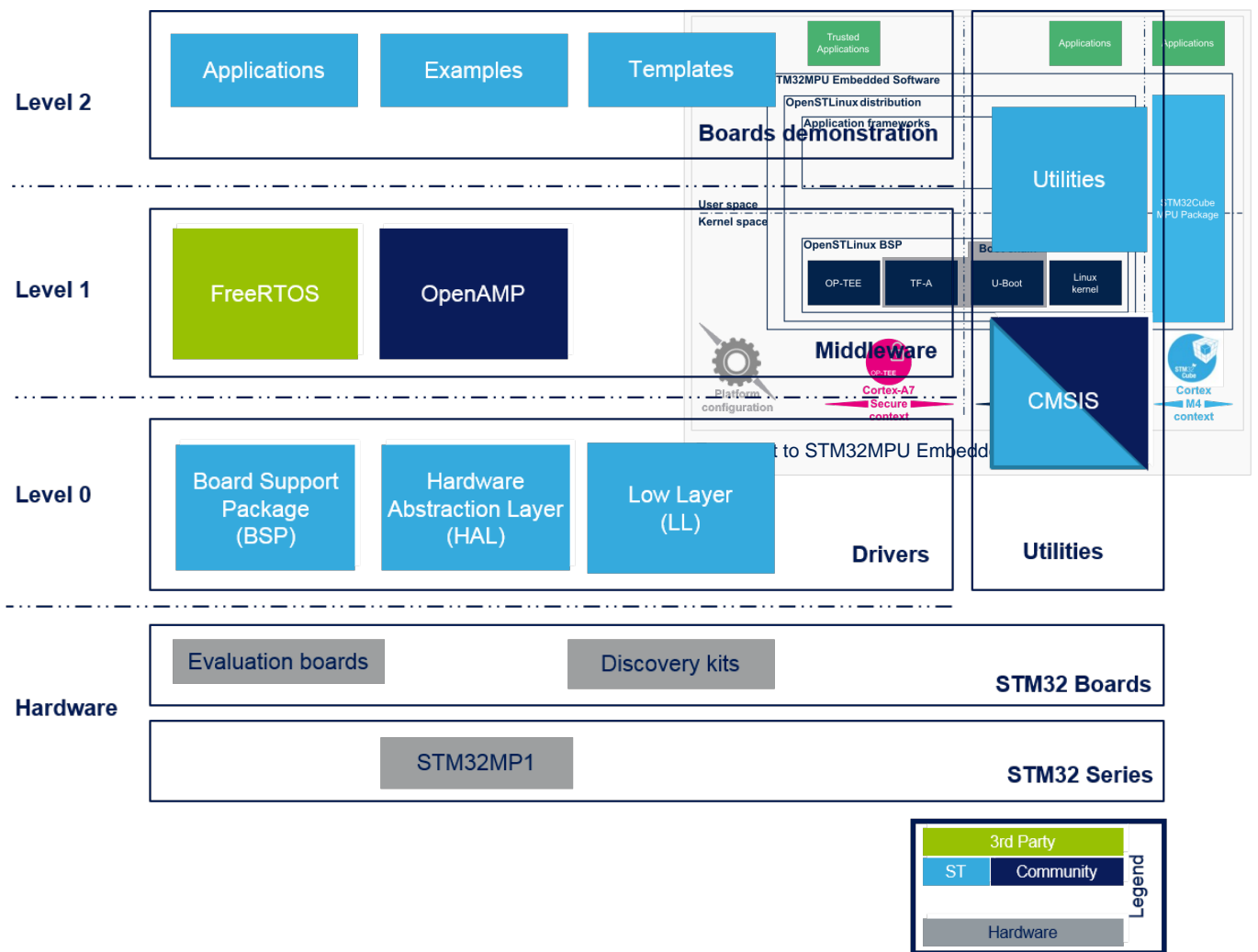
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
stm32mp1xx_ll_cortex.h	CORTEX LL Driver
stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
├── stm32mp15xx_disco_bus.c
├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

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2.5 CMSIS

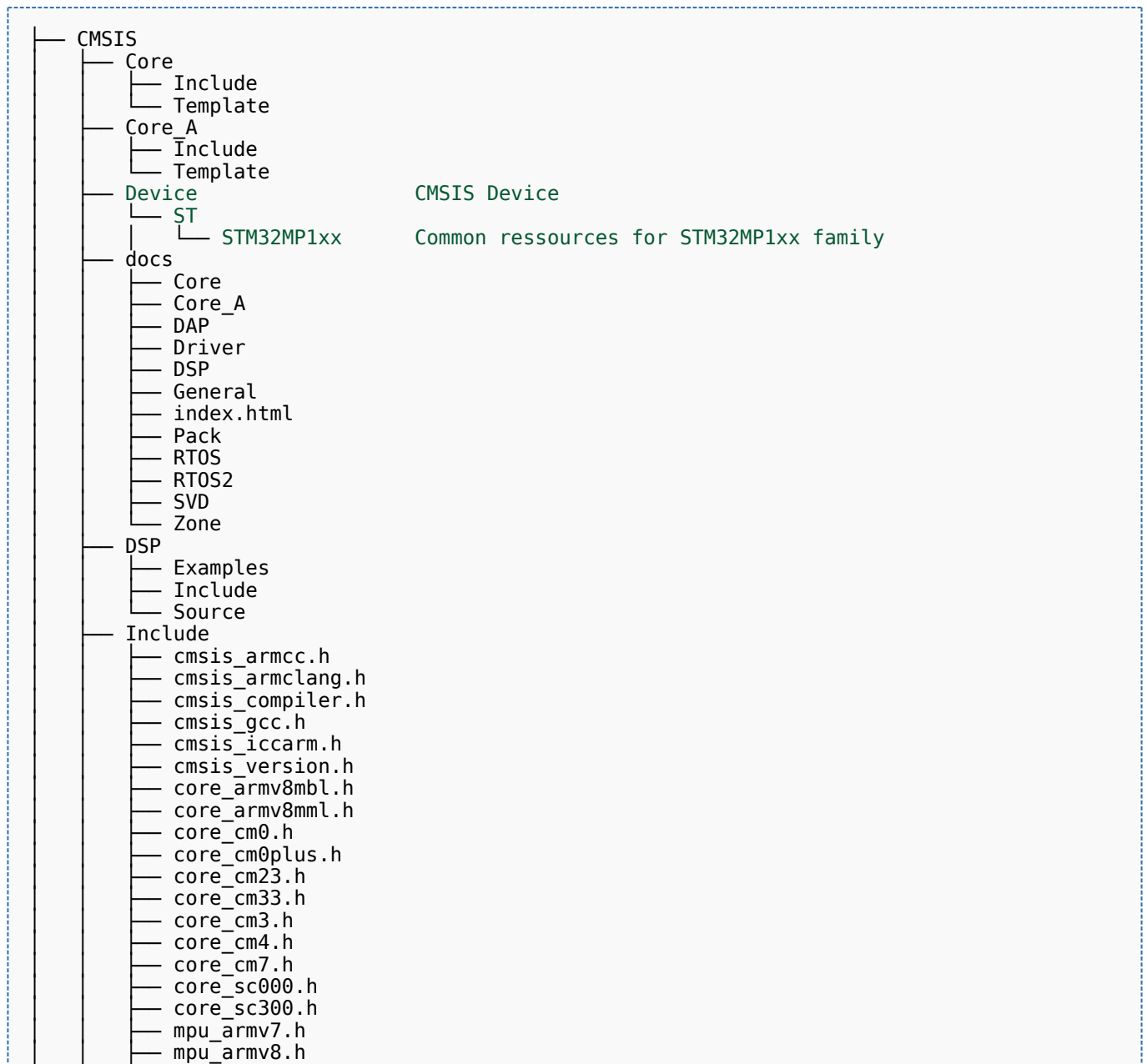
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- **CMSIS** structure overview:





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STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

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Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	76
2 STM32Cube MP1 Package architecture	77
2.1 Level 0 (Drivers)	78
2.1.1 HAL drivers	78
2.1.1.1 HAL drivers overview	78
2.1.1.2 List of HAL drivers	78
2.1.2 LL drivers	79
2.1.2.1 Low Layer drivers overview	79
2.1.2.2 List of LL drivers	80
2.1.3 BSP drivers	80
2.1.3.1 BSP drivers overview	80
2.1.3.2 List of BSP drivers	80
2.2 Level 1 (Middlewares)	81
2.2.1 OpenAMP	81
2.2.2 FreeRTOS	81
2.3 Level 2 (Boards demonstrations)	82
2.4 Utilities	82
2.5 CMSIS	83
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	86
4 References	87



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

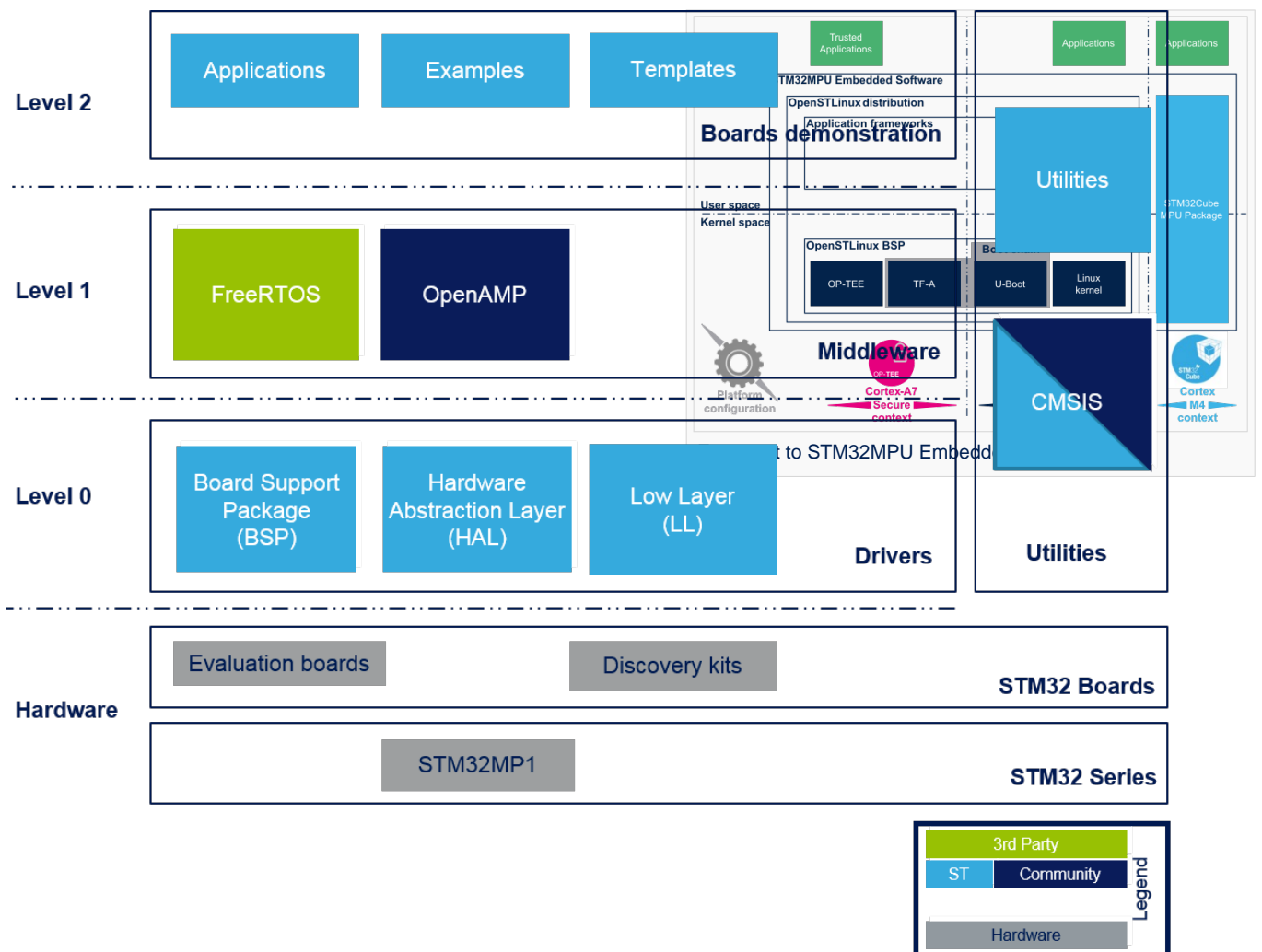
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On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



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- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

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Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

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stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
stm32mp1xx_ll_cortex.h	CORTEX LL Driver
stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
├── stm32mp15xx_disco_bus.c
├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
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    ├── stm32mp15xx_eval.c
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    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory footprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager  Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

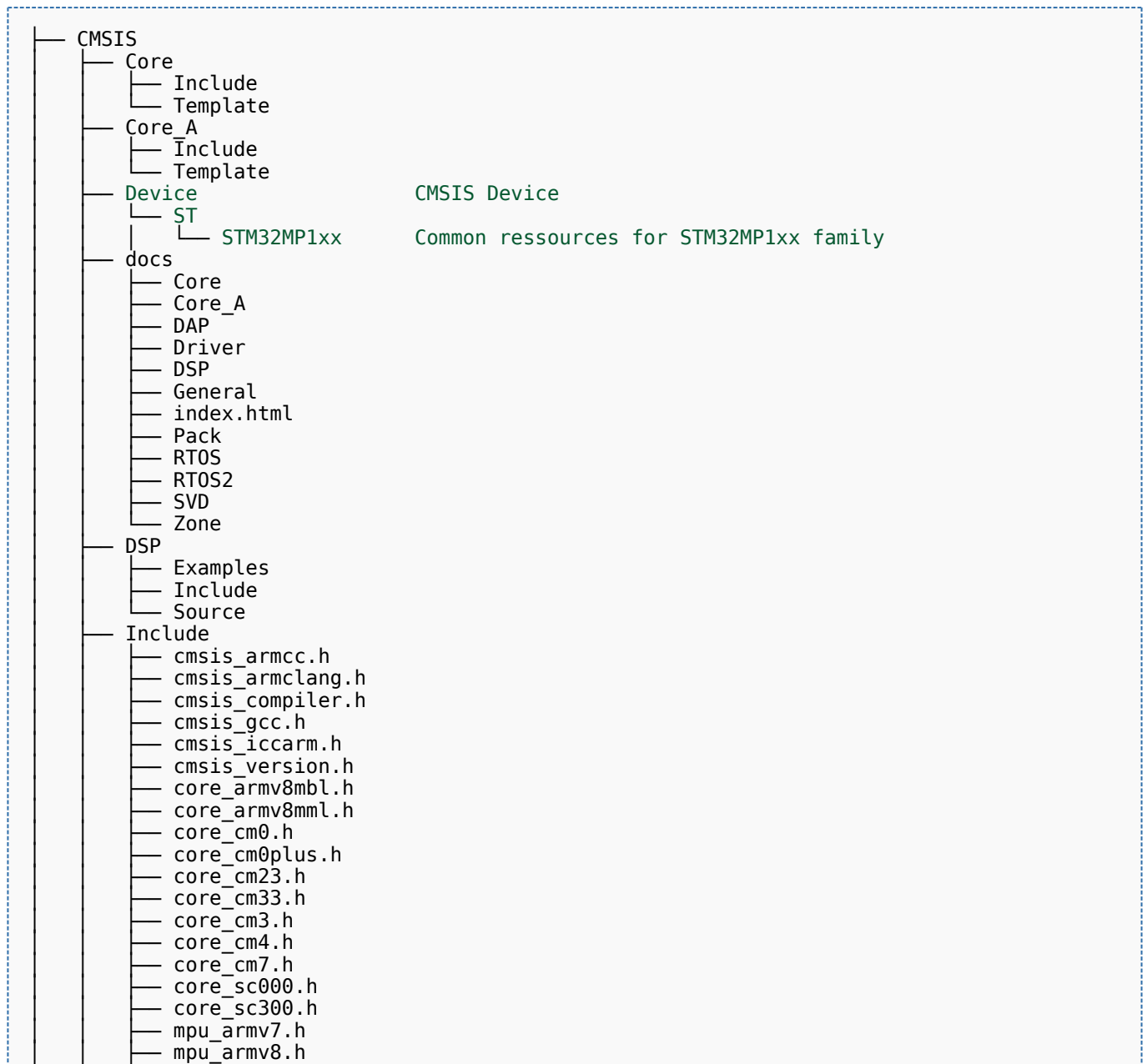
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

- The middleware and BSP components offer is smaller in **STM32Cube MP1 Package** as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
- All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - [OpenAMP](#) middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - [Resource Manager](#) library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load **STM32Cube MPU** firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

Stable: ~~Not stable~~ / Revision: 30.11.2021 - 17:43

Contents

1 Introduction	88
2 STM32Cube MP1 Package architecture	89
2.1 Level 0 (Drivers)	90
2.1.1 HAL drivers	90
2.1.1.1 HAL drivers overview	90
2.1.1.2 List of HAL drivers	90
2.1.2 LL drivers	91
2.1.2.1 Low Layer drivers overview	91
2.1.2.2 List of LL drivers	92
2.1.3 BSP drivers	92
2.1.3.1 BSP drivers overview	92
2.1.3.2 List of BSP drivers	92
2.2 Level 1 (Middlewares)	93
2.2.1 OpenAMP	93
2.2.2 FreeRTOS	93
2.3 Level 2 (Boards demonstrations)	94
2.4 Utilities	94
2.5 CMSIS	95
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	98
4 References	99



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

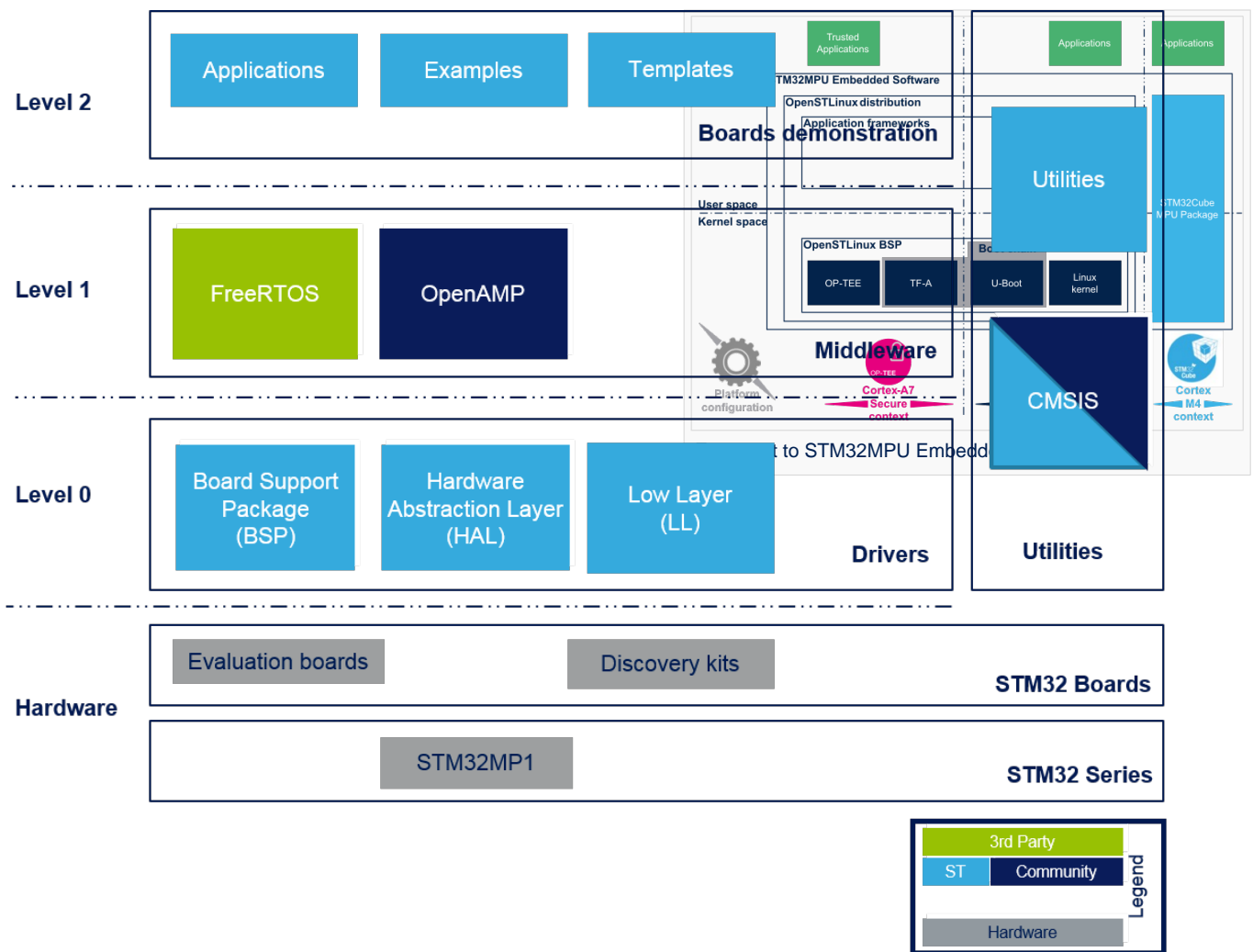
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
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stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
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stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



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├── Release_Notes.html
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├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
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    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
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    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h

```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocesor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
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Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

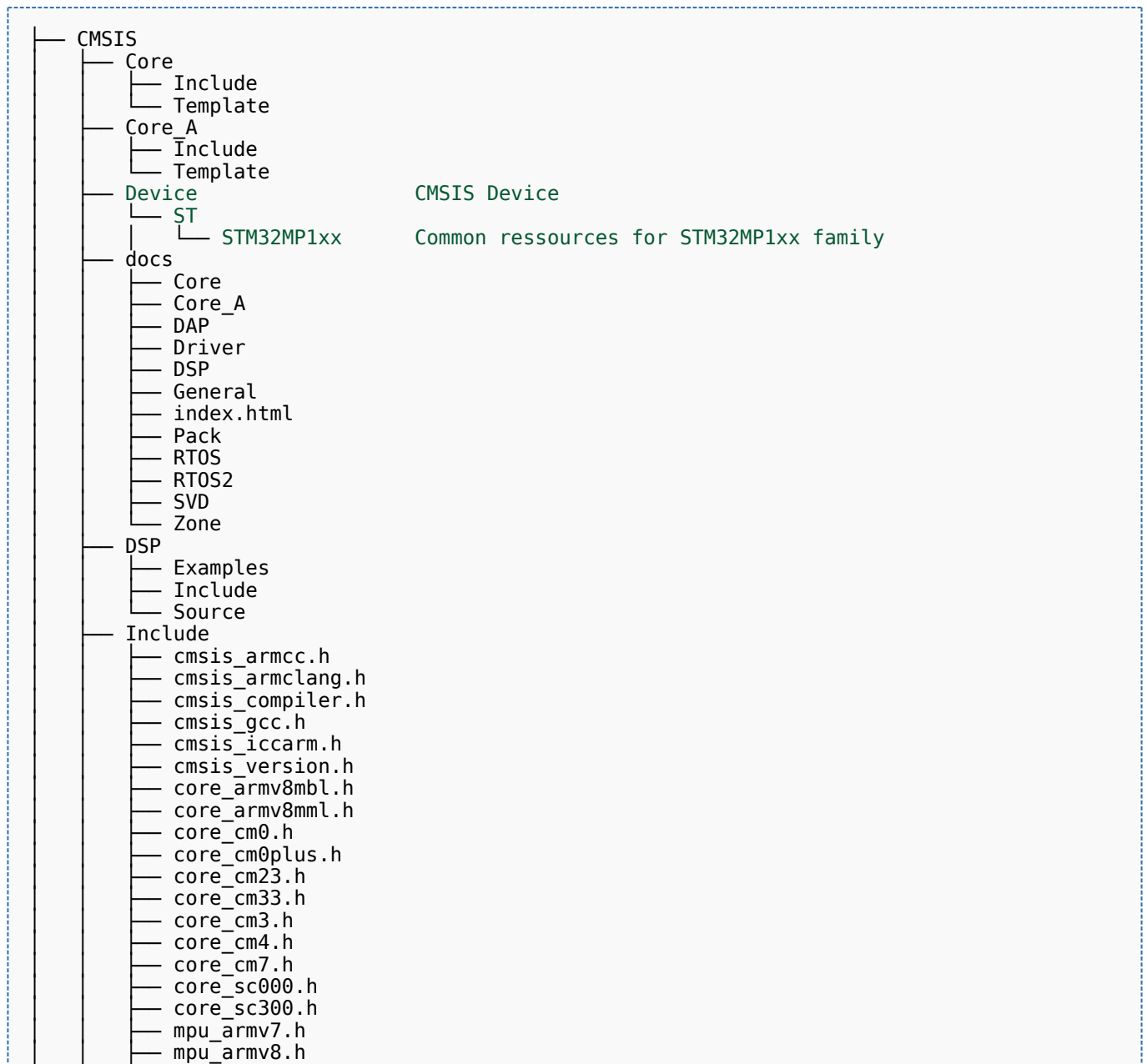
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The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

- The middleware and BSP components offer is smaller in **STM32Cube MP1 Package** as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
- All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - [OpenAMP](#) middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - [Resource Manager](#) library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load **STM32Cube MPU** firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	100
2 STM32Cube MP1 Package architecture	101
2.1 Level 0 (Drivers)	102
2.1.1 HAL drivers	102
2.1.1.1 HAL drivers overview	102
2.1.1.2 List of HAL drivers	102
2.1.2 LL drivers	103
2.1.2.1 Low Layer drivers overview	103
2.1.2.2 List of LL drivers	104
2.1.3 BSP drivers	104
2.1.3.1 BSP drivers overview	104
2.1.3.2 List of BSP drivers	104
2.2 Level 1 (Middlewares)	105
2.2.1 OpenAMP	105
2.2.2 FreeRTOS	105
2.3 Level 2 (Boards demonstrations)	106
2.4 Utilities	106
2.5 CMSIS	107
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	110
4 References	111



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

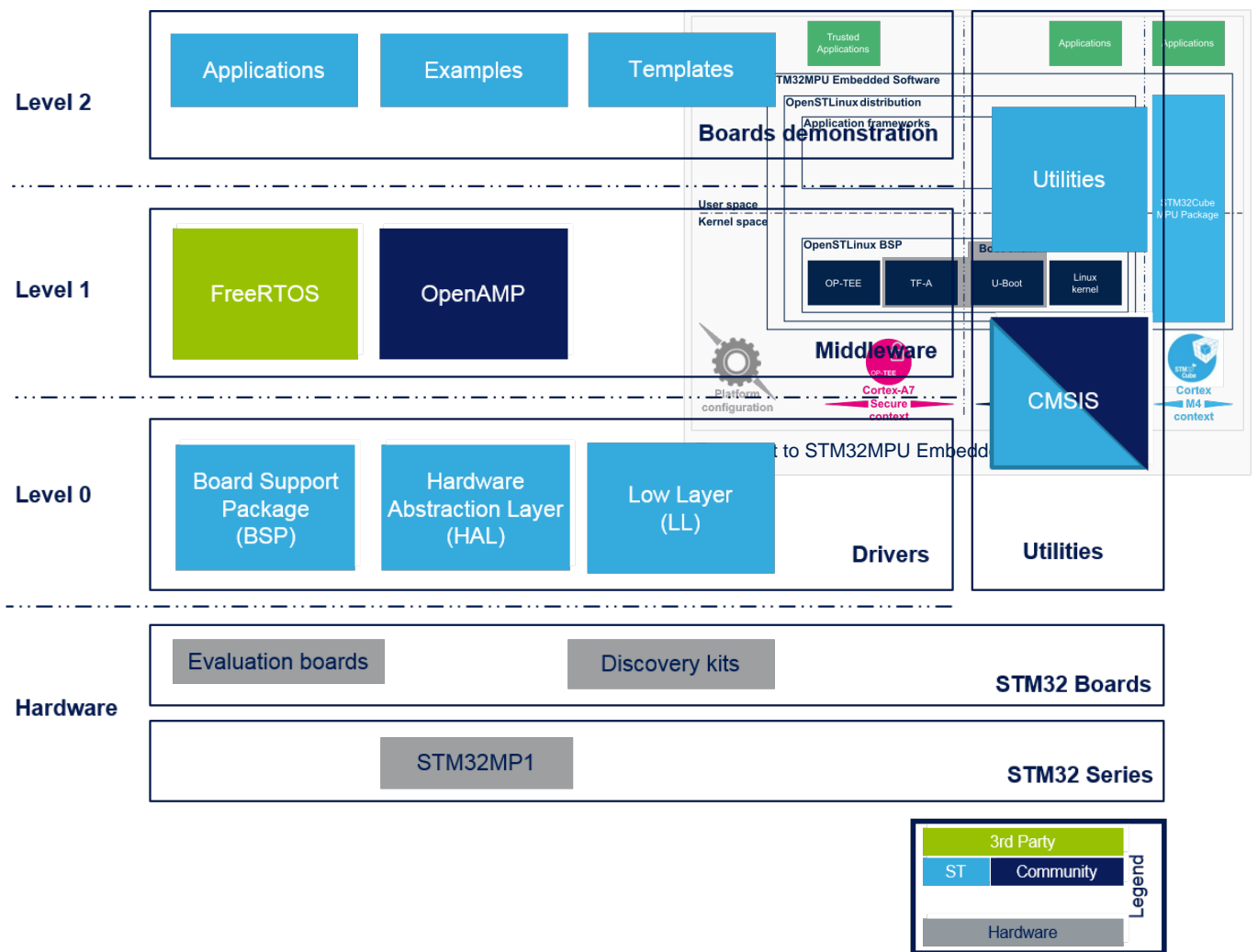
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

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stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
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stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
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stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
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stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

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stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
├── stm32mp15xx_disco_bus.c
├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : [OpenAMP](#) and [FreeRTOS](#)

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

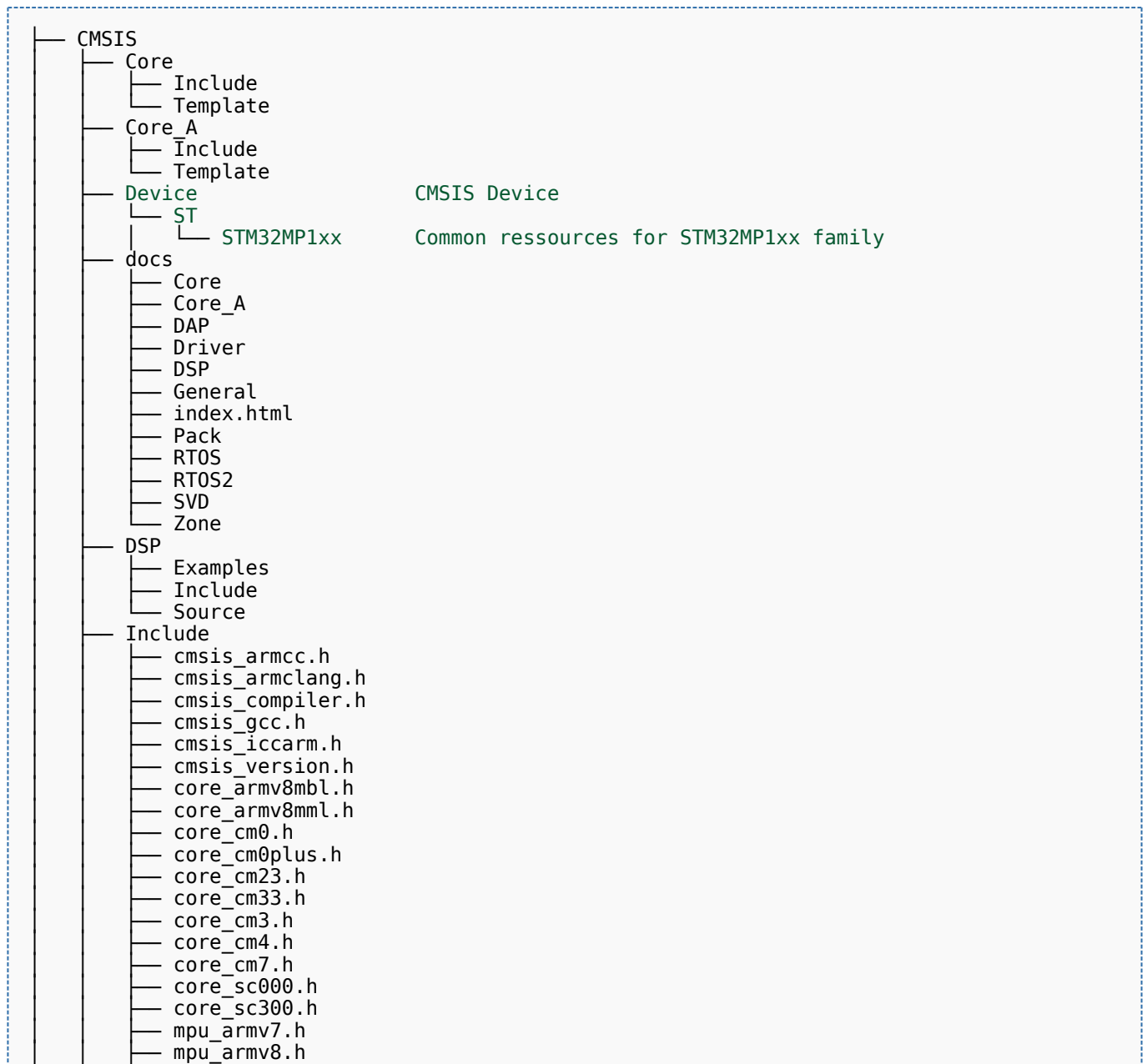
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

- The middleware and BSP components offer is smaller in **STM32Cube MP1 Package** as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
- All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - [OpenAMP](#) middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
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Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	112
2 STM32Cube MP1 Package architecture	113
2.1 Level 0 (Drivers)	114
2.1.1 HAL drivers	114
2.1.1.1 HAL drivers overview	114
2.1.1.2 List of HAL drivers	114
2.1.2 LL drivers	115
2.1.2.1 Low Layer drivers overview	115
2.1.2.2 List of LL drivers	116
2.1.3 BSP drivers	116
2.1.3.1 BSP drivers overview	116
2.1.3.2 List of BSP drivers	116
2.2 Level 1 (Middlewares)	117
2.2.1 OpenAMP	117
2.2.2 FreeRTOS	117
2.3 Level 2 (Boards demonstrations)	118
2.4 Utilities	118
2.5 CMSIS	119
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	122
4 References	123



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

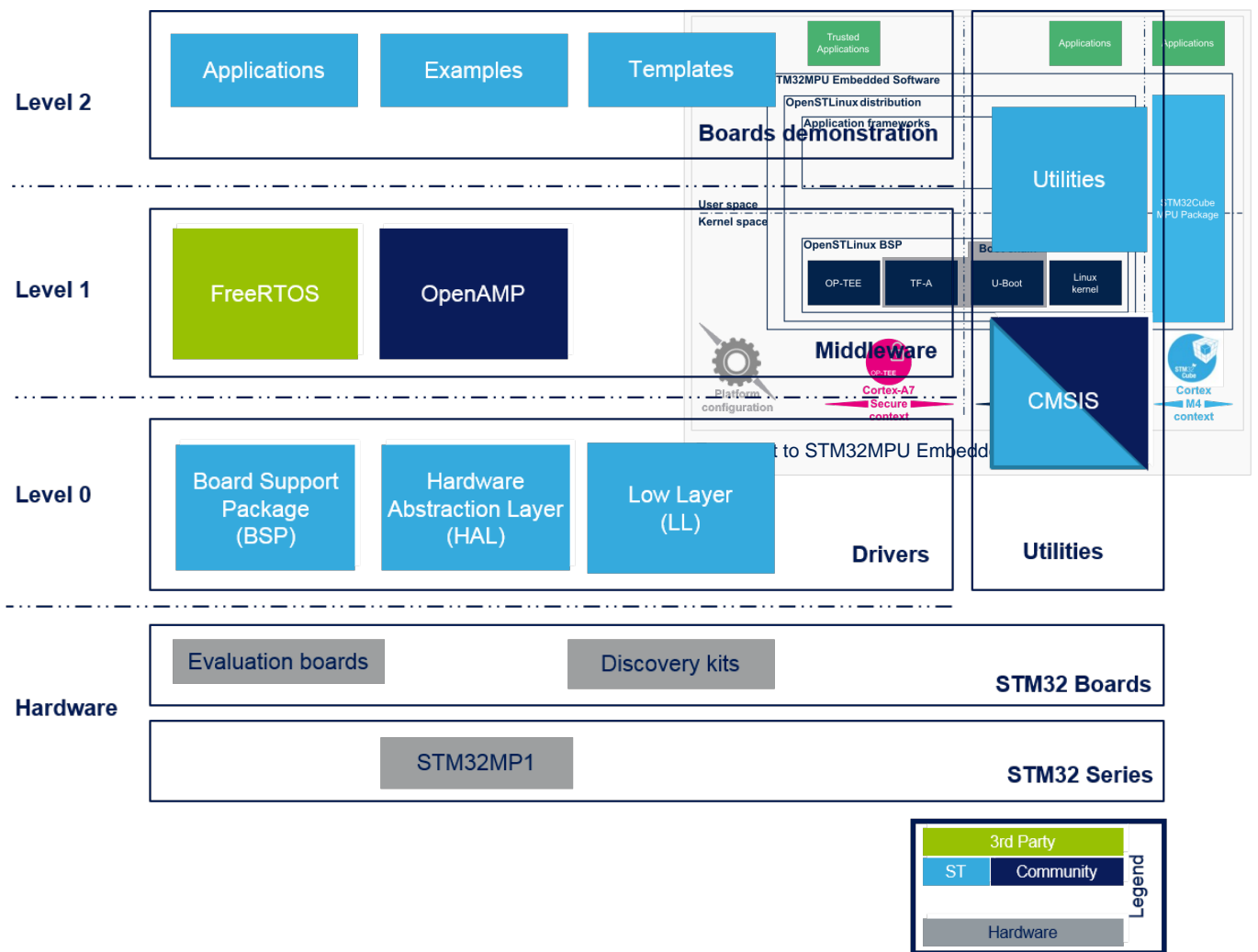
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

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- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

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Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

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stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
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stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
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├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
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    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

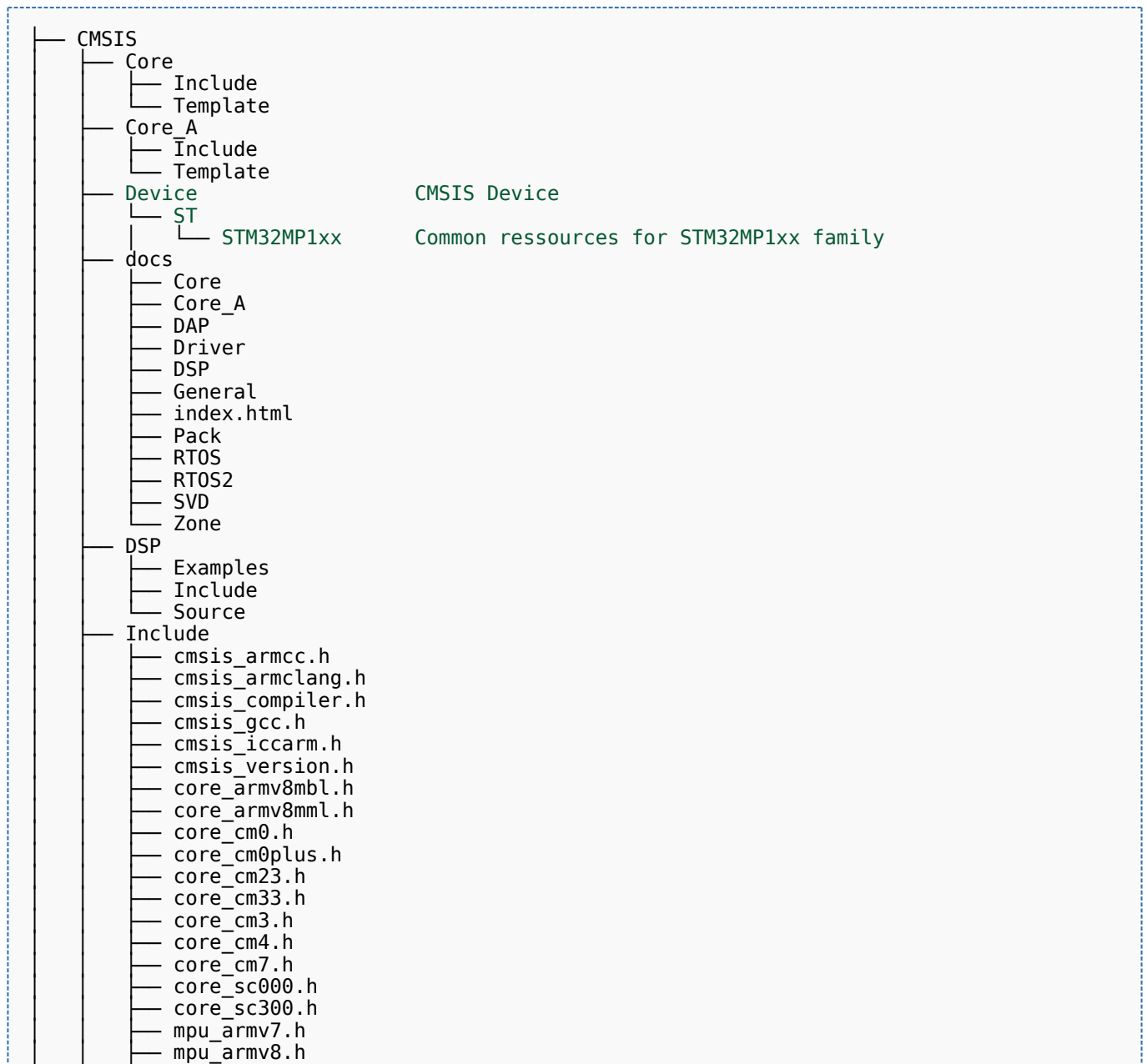
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	124
2 STM32Cube MP1 Package architecture	125
2.1 Level 0 (Drivers)	126
2.1.1 HAL drivers	126
2.1.1.1 HAL drivers overview	126
2.1.1.2 List of HAL drivers	126
2.1.2 LL drivers	127
2.1.2.1 Low Layer drivers overview	127
2.1.2.2 List of LL drivers	128
2.1.3 BSP drivers	128
2.1.3.1 BSP drivers overview	128
2.1.3.2 List of BSP drivers	128
2.2 Level 1 (Middlewares)	129
2.2.1 OpenAMP	129
2.2.2 FreeRTOS	129
2.3 Level 2 (Boards demonstrations)	130
2.4 Utilities	130
2.5 CMSIS	131
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	134
4 References	135



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

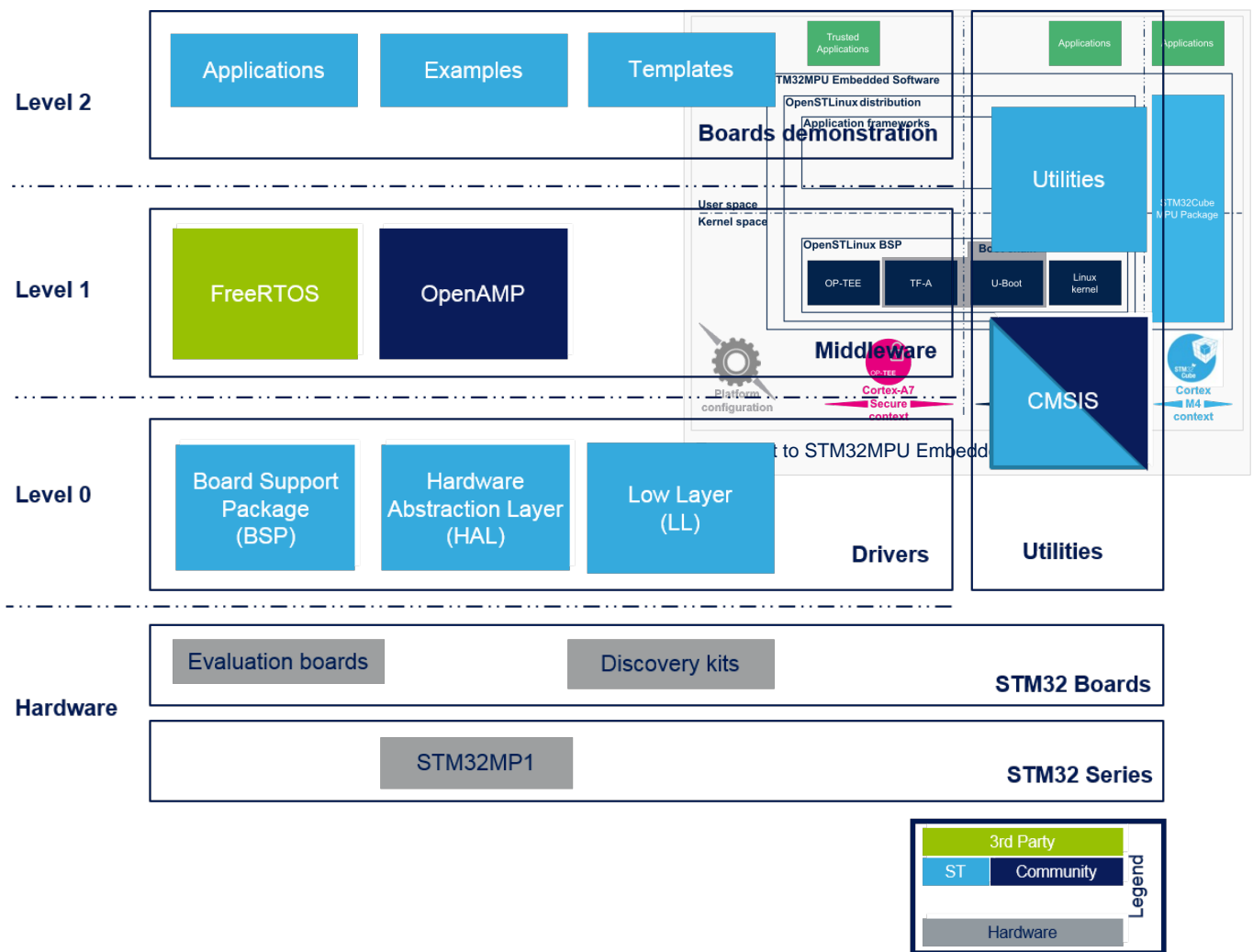
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
stm32mp1xx_ll_cortex.h	CORTEX LL Driver
stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
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2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

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The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

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    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory footprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
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- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

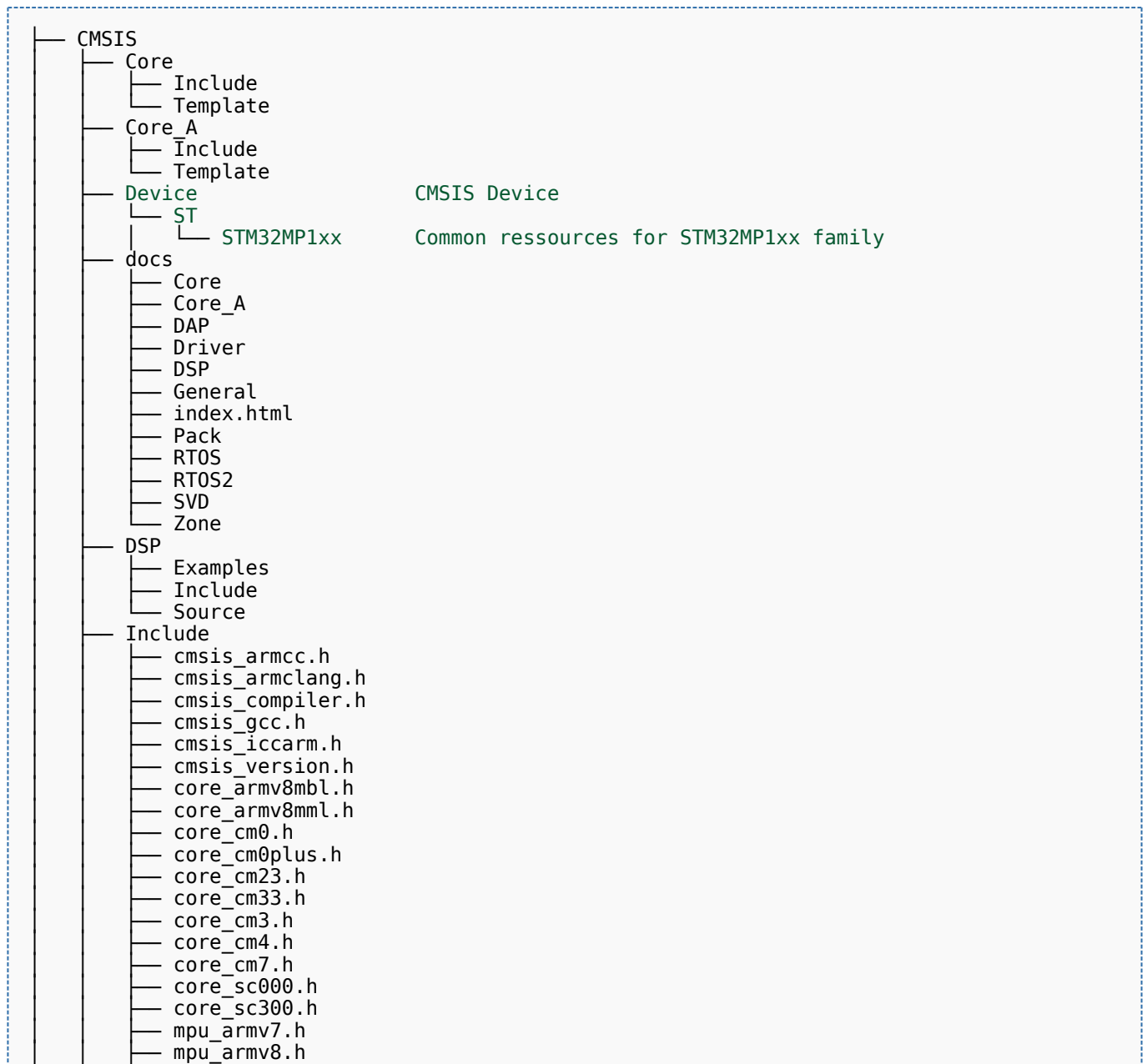
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The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offered are smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux® running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processor between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	136
2 STM32Cube MP1 Package architecture	137
2.1 Level 0 (Drivers)	138
2.1.1 HAL drivers	138
2.1.1.1 HAL drivers overview	138
2.1.1.2 List of HAL drivers	138
2.1.2 LL drivers	139
2.1.2.1 Low Layer drivers overview	139
2.1.2.2 List of LL drivers	140
2.1.3 BSP drivers	140
2.1.3.1 BSP drivers overview	140
2.1.3.2 List of BSP drivers	140
2.2 Level 1 (Middlewares)	141
2.2.1 OpenAMP	141
2.2.2 FreeRTOS	141
2.3 Level 2 (Boards demonstrations)	142
2.4 Utilities	142
2.5 CMSIS	143
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	146
4 References	147



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

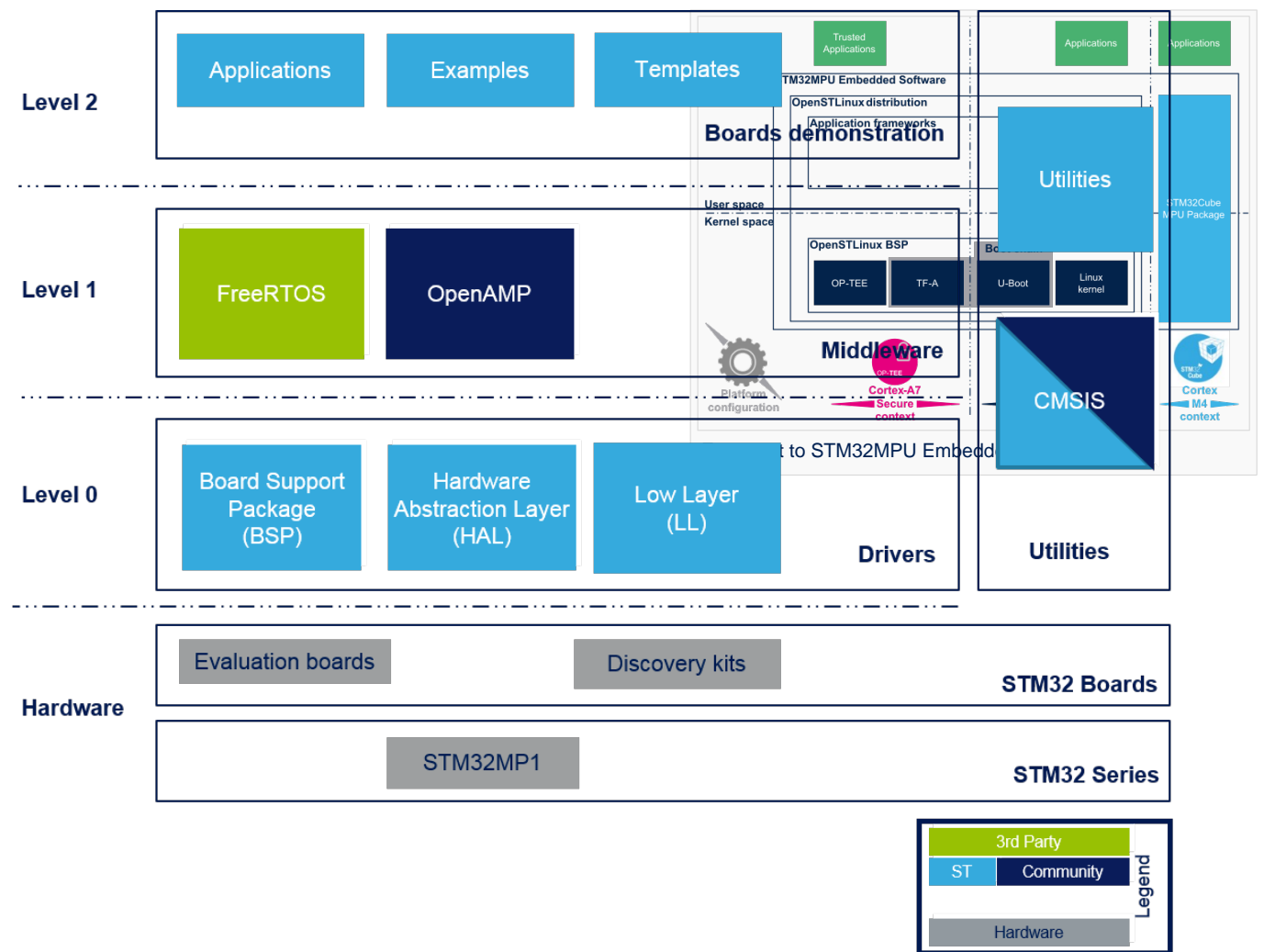
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

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stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
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├── Release_Notes.html
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├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
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    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : [OpenAMP](#) and [FreeRTOS](#)

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory footprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

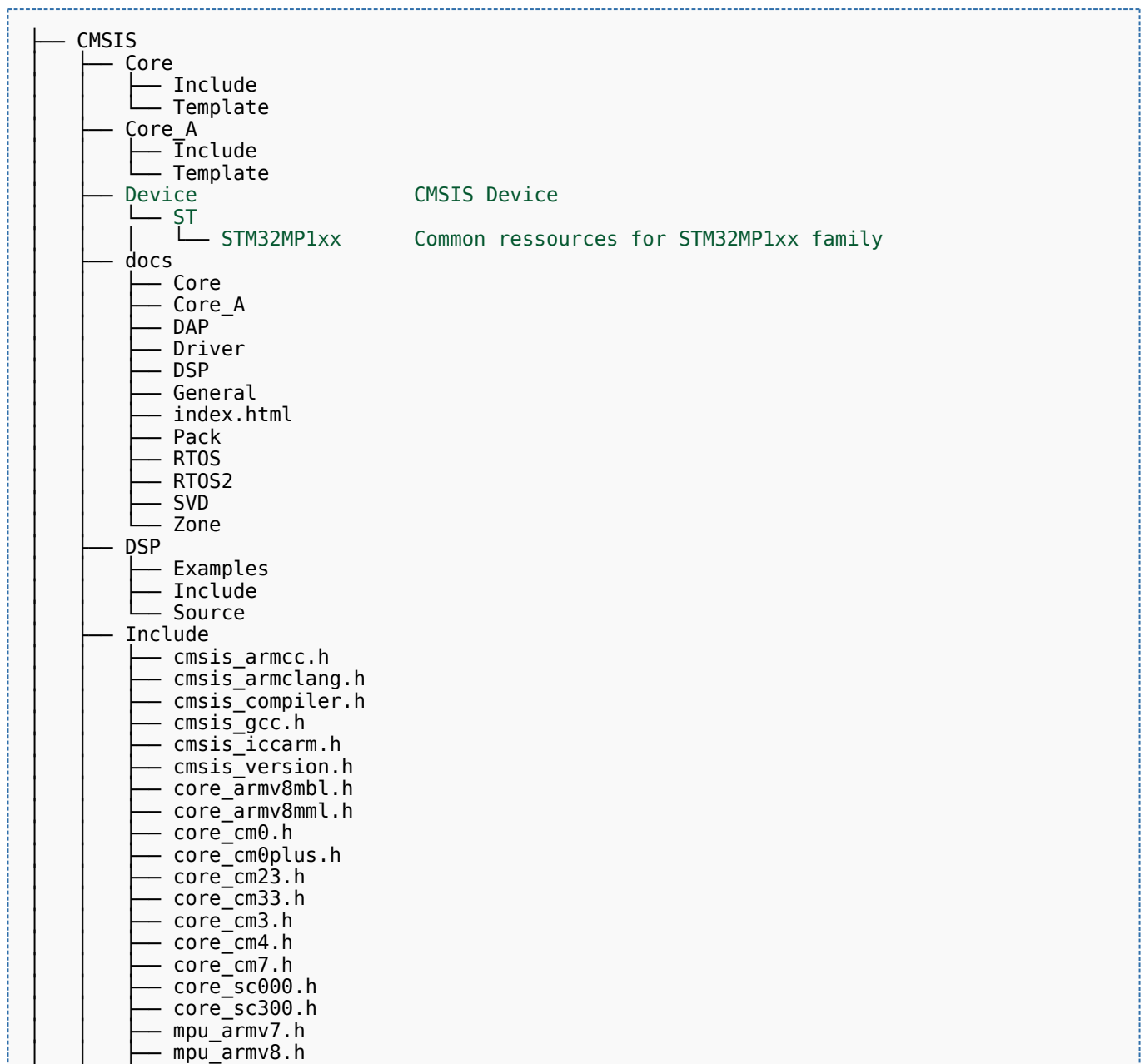
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

Stable: 02.08.2021 - 07:18 / Revision: 02.08.2021 - 07:17

Contents

1 Introduction	148
2 STM32Cube MP1 Package architecture	149
2.1 Level 0 (Drivers)	150
2.1.1 HAL drivers	150
2.1.1.1 HAL drivers overview	150
2.1.1.2 List of HAL drivers	150
2.1.2 LL drivers	151
2.1.2.1 Low Layer drivers overview	151
2.1.2.2 List of LL drivers	152
2.1.3 BSP drivers	152
2.1.3.1 BSP drivers overview	152
2.1.3.2 List of BSP drivers	152
2.2 Level 1 (Middlewares)	153
2.2.1 OpenAMP	153
2.2.2 FreeRTOS	153
2.3 Level 2 (Boards demonstrations)	154
2.4 Utilities	154
2.5 CMSIS	155
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	158
4 References	159



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

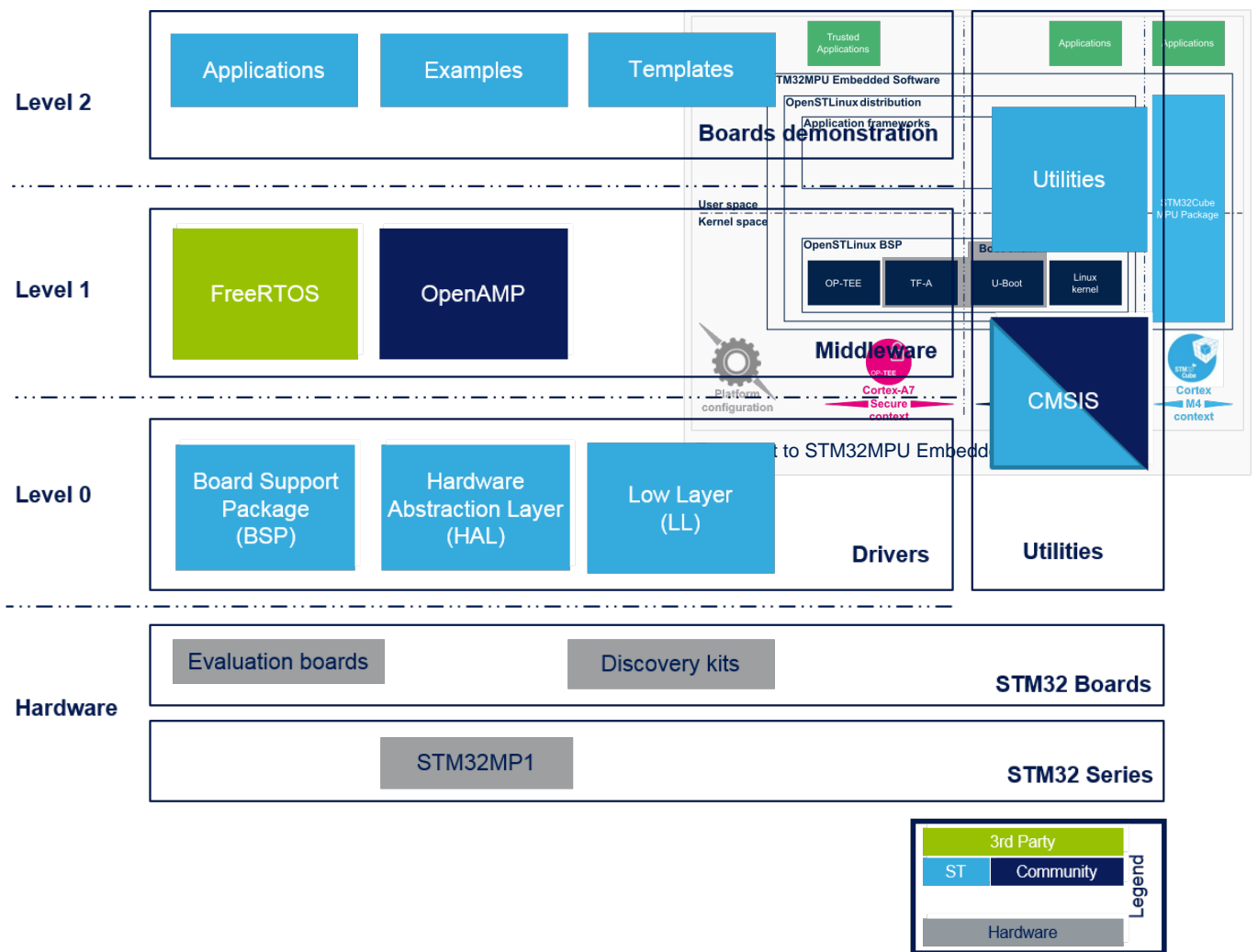
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
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2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

Information

Note:

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The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

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The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
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The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



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│   ├── stm32mp15xx_eval.h
│   ├── stm32mp15xx_eval_stpmic1.c
│   └── stm32mp15xx_eval_stpmic1.h

```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
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2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
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Information

Note:

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It includes the following main features :

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- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

- **Examples projects** showing how to use HAL APIs and Low Layer drivers if any (Level 0) with very basic usage of BSP layer (buttons and LEDs in general)
- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
- **Demonstrations projects** showing how to integrate and run a maximum number of peripherals and Middleware stacks to showcase the product features and performance
- **Templates projects** is a really basic user application including IDE projects files, which could be used to start a custom project

Information

Notes:

- Please refer to [STM32Cube MP1 Package Overview](#) to get information on locating Examples, Applications and Demonstrations in **STM32Cube MP1 Package**
- Please refer to [List of projects](#) to get information on the list of available Examples, Applications and Demonstrations in **STM32Cube MP1 Package**

2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager  Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

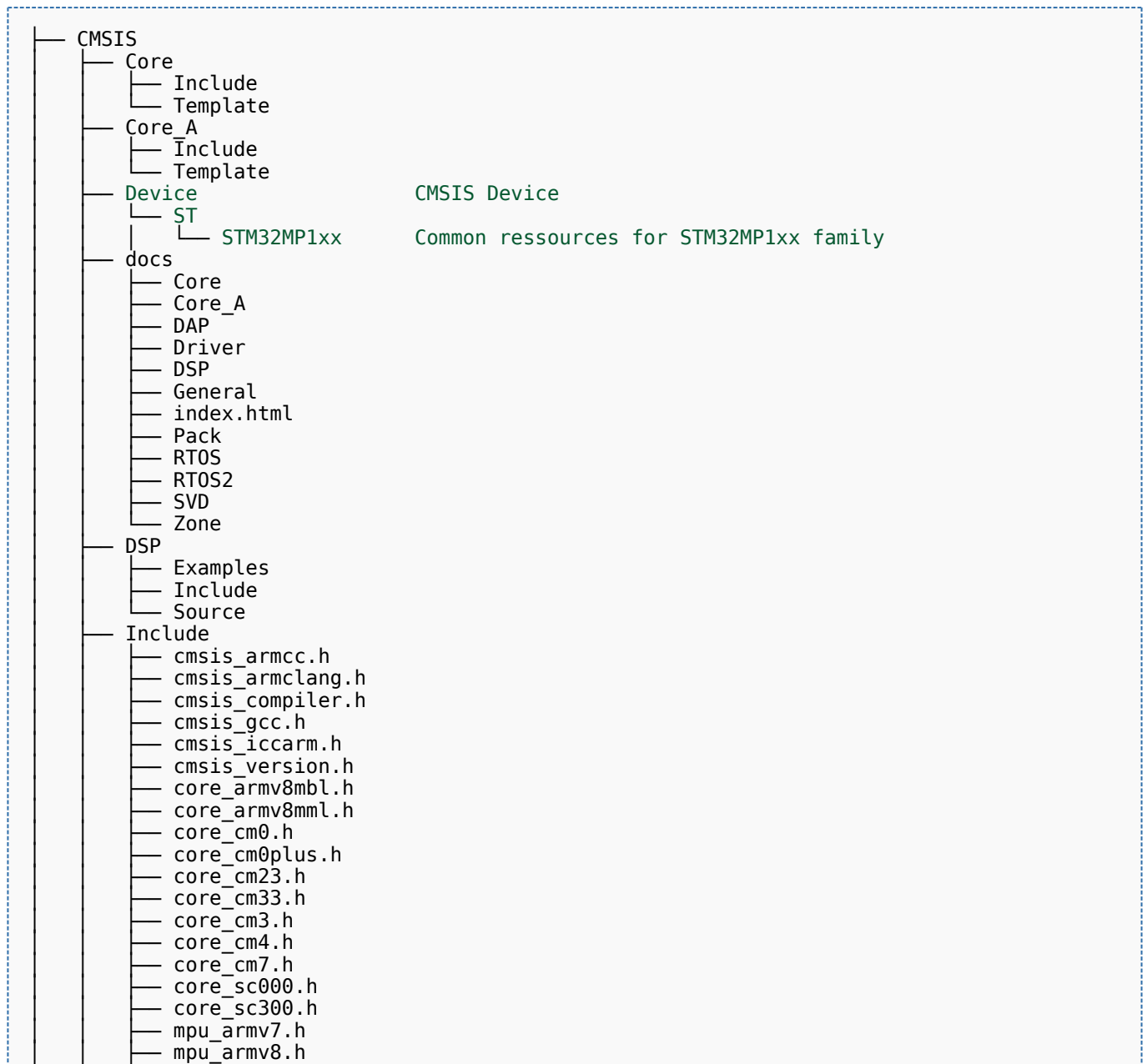
The **Cortex Microcontroller Software Interface Standard** (CMSIS) is a vendor-independent hardware abstraction layer for the Cortex-M processor series.

- Please refer to article [CMSIS](#) to get more information on CMSIS component

The CMSIS component also provides specific common resources for device support. It enables consistent and simple software interfaces to the processor and the peripherals, simplifying software re-use, reducing the learning curve for microcontroller developers, and reducing the time to market for new devices

This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between STM32Cube MP1 Package and STM32Cube MCU Package:

- The middleware and BSP components offer is smaller in STM32Cube MP1 Package as we can take advantage of a rich OS like Linux[®] running on Cortex-A core for networking, USB, visual and audio services

Information

Notes:

- All Middlewares provided by STM32Cube MCU Package should be compatible with MPU environment even if not provided in STM32Cube MP1 Package (it means they are not tested)
- All BSP components provided by STM32Cube MCU Package are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
 - OpenAMP middleware for Intercommunication processeur between cortex A and cortex M (RPMsg protocol implementation)
 - Resource Manager library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load STM32Cube MPU firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter

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Contents

1 Introduction	160
2 STM32Cube MP1 Package architecture	161
2.1 Level 0 (Drivers)	162
2.1.1 HAL drivers	162
2.1.1.1 HAL drivers overview	162
2.1.1.2 List of HAL drivers	162
2.1.2 LL drivers	163
2.1.2.1 Low Layer drivers overview	163
2.1.2.2 List of LL drivers	164
2.1.3 BSP drivers	164
2.1.3.1 BSP drivers overview	164
2.1.3.2 List of BSP drivers	164
2.2 Level 1 (Middlewares)	165
2.2.1 OpenAMP	165
2.2.2 FreeRTOS	165
2.3 Level 2 (Boards demonstrations)	166
2.4 Utilities	166
2.5 CMSIS	167
3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package	170
4 References	171



1 Introduction

This article introduces **STM32Cube MP1 Package** architecture based on the Arm[®] Cortex[®]-M processor (e.g. Arm Cortex-M4)

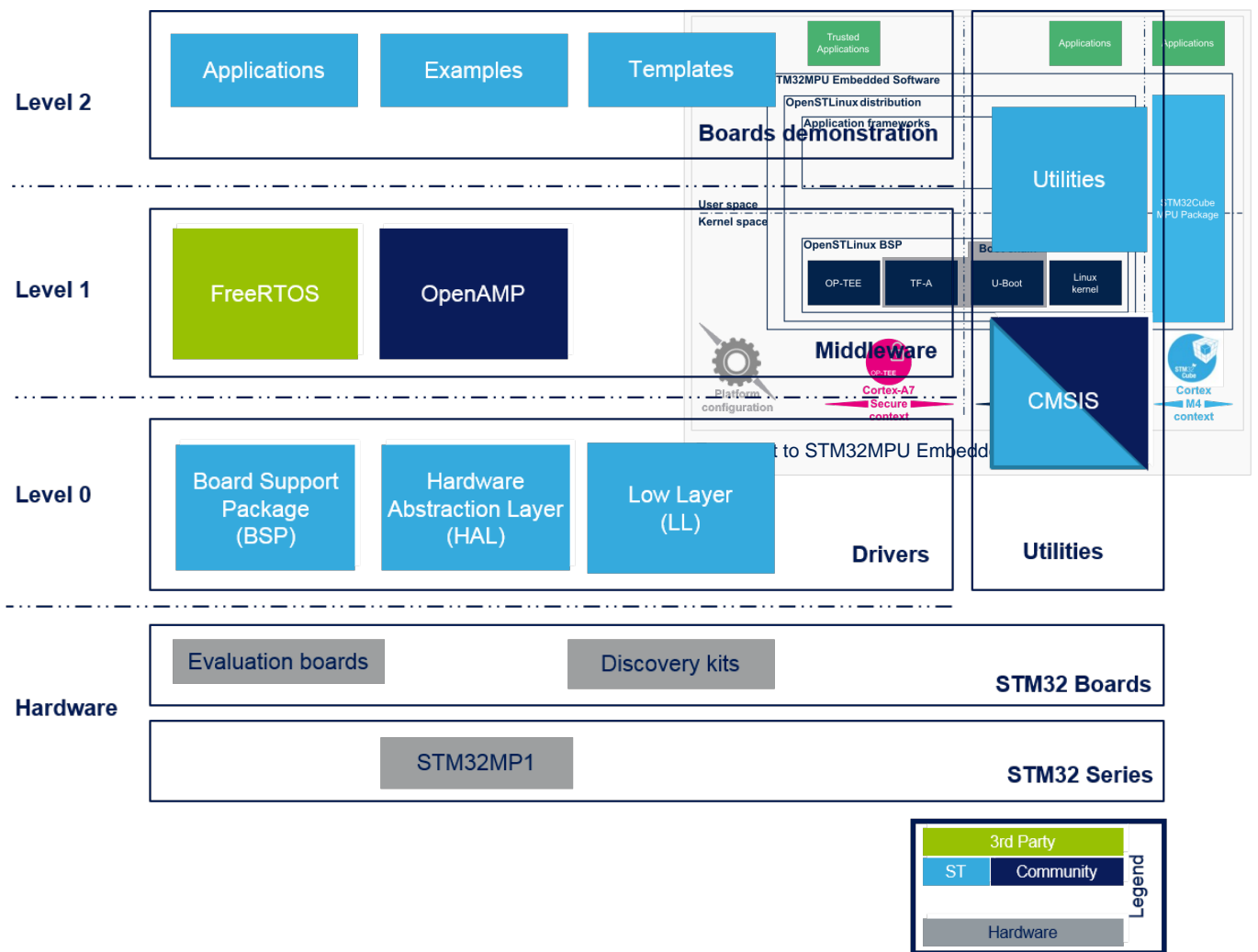
- Please refer to [STM32Cube MP1 Package](#) article to get started.



2 STM32Cube MP1 Package architecture

The **STM32Cube MP1 Package** gathers together, in a single package, all the generic embedded software components required to develop applications on top of Cortex-M microprocessors.

On top of the hardware, the **STM32Cube MP1 Package** solution is built around three levels of software components (Level 0 for Drivers, level 1 for Middlewares, Level 2 for Boards demonstrations), that interact easily with each other. It also includes 2 common components CMSIS and Utilities which interact with all three levels.



Information

Notes:

- **HAL drivers** deal with the STM32 "internal" devices: they are related to the STM32MP15 internal peripherals
- **BSP drivers** deal with the boards configuration and high-level APIs: they are the equivalent of the Linux DT mechanism (Device tree or STM32MP15 device tree) and of the Linux frameworks (Linux application frameworks overview)



2.1 Level 0 (Drivers)

This level is divided into three software components:

- **Hardware Abstraction Layer (HAL)**
- **Low Layer (LL)**
- **Board Support Package (BSP)**

2.1.1 HAL drivers

The **HAL drivers** provide the low level drivers and the hardware interfacing methods to interact with the upper layers (application, libraries and stacks). They provide generic, multi instance and function-oriented APIs which simplify user application implementation by providing ready-to-use processes.

As example, for the communication peripherals (I2C, UART...), they include APIs allowing to initialize and configure the peripheral, to manage data transfer based on polling, interrupt or DMA process, and to handle communication errors that may raise during communication.

i Information

Note:

- Please refer to [STM32MP15 reference manuals](#) to get detailed information about all supported IPs of STM32MP15xx family

2.1.1.1 HAL drivers overview

The HAL APIs layer is composed of native and extended APIs set. It is directly built around a generic architecture and allows the build-upon layers, like the middleware layer, to implement its functions without in-depth knowledge about the used STM32 device. This improves the library code reusability and guarantees an easy portability on other devices and STM32 families

Contrary to the low layer drivers (see HAL Low Layer section), the HAL ones are functionality-oriented and not IP-oriented, Example: for the Timer peripheral, the APIs could be split into several categories following the functions offered by the IPs (Basic timer, capture, PWM ...etc.).

The HAL Drivers are a set of common APIs with a high compliancy level with most of the clients available on the market (stacks) called native APIs and embed also some extended functionalities for special services or a combination of several features offered by the STM32 peripherals

The HAL drivers APIs are split in two categories:

- Generic APIs which provide common and generic functions to all the STM32 Series
- Extension APIs which provide specific customized functions for a specific family or a specific part number

2.1.1.2 List of HAL drivers

Please find hereafter the list of HAL drivers available for STM32MP1xx family :

i Information

Note:

- Please refer to [List of HAL Drivers](#) to get full list of delivered HAL drivers

— stm32mp1xx_hal_adc.c	ADC HAL Driver
— stm32mp1xx_hal_adc_ex.c	ADC Extended HAL Driver
— stm32mp1xx_hal_cec.c	CEC HAL Driver
— stm32mp1xx_hal_cortex.c	CORTEX HAL Driver
— stm32mp1xx_hal_crc.c	CRC HAL Driver



stm32mp1xx_hal_crc_ex.c	CRC Extended HAL Driver
stm32mp1xx_hal_cryp.c	CRYP HAL Driver
stm32mp1xx_hal_cryp_ex.c	CRYP Extended HAL Driver
stm32mp1xx_hal_dac.c	DAC HAL Driver
stm32mp1xx_hal_dac_ex.c	DAC Extended HAL Driver
stm32mp1xx_hal_dcmi.c	DCMI HAL Driver
stm32mp1xx_hal_dfstm.c	DFSDM HAL Driver
stm32mp1xx_hal_dfstm_ex.c	DFSDM Extended HAL Driver
stm32mp1xx_hal_dma.c	DMA HAL Driver
stm32mp1xx_hal_dma_ex.c	DMA Extended HAL Driver
stm32mp1xx_hal_exti.c	EXTI HAL Driver
stm32mp1xx_hal_fdcan.c	FDCAN HAL Driver
stm32mp1xx_hal_gpio.c	GPIO HAL Driver
stm32mp1xx_hal_gpio_ex.c	GPIO Extended HAL Driver
stm32mp1xx_hal_hash.c	HASH HAL Driver
stm32mp1xx_hal_hash_ex.c	HASH Extended HAL Driver
stm32mp1xx_hal_hsem.c	HSEM HAL Driver
stm32mp1xx_hal_i2c.c	I2C HAL Driver
stm32mp1xx_hal_i2c_ex.c	I2C Extended HAL Driver
stm32mp1xx_hal_ipcc.c	IPCC HAL Driver
stm32mp1xx_hal_lptim.c	LPTIM HAL Driver
stm32mp1xx_hal_mdios.c	MDIOS HAL Driver
stm32mp1xx_hal_mdma.c	MDMA HAL Driver
stm32mp1xx_hal_pwr.c	PWR HAL Driver
stm32mp1xx_hal_pwr_ex.c	PWR Extended HAL Driver
stm32mp1xx_hal_qspi.c	QSPI HAL Driver
stm32mp1xx_hal_rcc.c	RCC HAL Driver
stm32mp1xx_hal_rcc_ex.c	RCC Extended HAL Driver
stm32mp1xx_hal_rng.c	RNG HAL Driver
stm32mp1xx_hal_rtc.c	RTC HAL Driver
stm32mp1xx_hal_rtc_ex.c	RTC Extended HAL Driver
stm32mp1xx_hal_sai.c	SAI HAL Driver
stm32mp1xx_hal_sai_ex.c	SAI Extended HAL Driver
stm32mp1xx_hal_sd.c	SD HAL Driver
stm32mp1xx_hal_smartcard.c	SMARTCARD HAL Driver
stm32mp1xx_hal_smartcard_ex.c	SMARTCARD Extended HAL Driver
stm32mp1xx_hal_smbus.c	SMBUS HAL Driver
stm32mp1xx_hal_spdifrx.c	SPDIFRX HAL Driver
stm32mp1xx_hal_spi.c	SPI HAL Driver
stm32mp1xx_hal_spi_ex.c	SPI Extended HAL Driver
stm32mp1xx_hal_sram.c	FMC HAL Driver (for PSRAM)
stm32mp1xx_hal_tim.c	TIM HAL Driver
stm32mp1xx_hal_tim_ex.c	TIM Extended HAL Driver
stm32mp1xx_hal_uart.c	UART HAL Driver
stm32mp1xx_hal_uart_ex.c	UART Extended HAL Driver
stm32mp1xx_hal_usart.c	USART HAL Driver
stm32mp1xx_hal_usart_ex.c	USART Extended HAL Driver
stm32mp1xx_hal_wwdg.c	WWDG HAL Driver

2.1.2 LL drivers

The **Low Layer (LL) drivers** offer a fast light-weight expert-oriented layer which is closer to the hardware than the HAL. The LL APIs are available only for a set of peripherals

2.1.2.1 Low Layer drivers overview

The Low Layer (LL) drivers are part of the STM32Cube firmware HAL that provides basic set of optimized and one-shot services. The Low layer drivers, contrary to the HAL ones are not Fully Portable across the STM32 families; the availability of some functions depends on the physical availability of the relative features on the product.

The Low Layer (LL) drivers are designed to offer the following features:

- New set of inline functions for direct and atomic register access
- One-shot operations that can be used by the HAL drivers or from application level.



- Fully independent from HAL and can be used in standalone usage (without HAL drivers)
- Full feature coverage of all the supported peripherals

2.1.2.2 List of LL drivers

Please find hereafter the list of LL drivers available for STM32MP1xx family :

Information

Note:

- Please refer to [List of LL Drivers](#) to get full list of delivered LL drivers

stm32mp1xx_ll_adc.h	ADC LL Driver
stm32mp1xx_ll_bus.h	BUS LL Driver
stm32mp1xx_ll_cortex.h	CORTEX LL Driver
stm32mp1xx_ll_dma.h	DMA LL Driver
stm32mp1xx_ll_dmamux.h	DMAMUX LL Driver
stm32mp1xx_ll_exti.h	EXTI LL Driver
stm32mp1xx_ll_gpio.h	GPIO LL Driver
stm32mp1xx_ll_hsem.h	HSEM LL Driver
stm32mp1xx_ll_i2c.h	I2C LL Driver
stm32mp1xx_ll_ipcc.h	IPCC LL Driver
stm32mp1xx_ll_lptim.h	LPTIM LL Driver
stm32mp1xx_ll_pwr.h	PWR LL Driver
stm32mp1xx_ll_rcc.h	RCC LL Driver
stm32mp1xx_ll_rtc.h	RTC LL Driver
stm32mp1xx_ll_spi.h	SPI LL Driver
stm32mp1xx_ll_sram.h	FMC LL Driver (for PSRAM)
stm32mp1xx_ll_system.h	SYSTEM LL Driver (SYSCFG & DBGMCU)
stm32mp1xx_ll_tim.h	TIM LL Driver
stm32mp1xx_ll_usart.h	USART LL Driver
stm32mp1xx_ll_utils.h	UTILITIES LL Driver
stm32mp1xx_ll_wwdg.h	WWDG LL Driver

2.1.3 BSP drivers

The **BSP drivers** are firmware components based on the HAL drivers and provide a set of APIs relative to the hardware components in the evaluation boards coming with the **STM32Cube Package**. All examples and applications given with the **STM32Cube** are based on these BSP drivers.

2.1.3.1 BSP drivers overview

The BSP architecture proposes a new model that prevents some Standard library weaknesses and provides more features:

- Portable external resources code (components): the external components could be used by all STM32 families.
- Multiple use of hardware resources without duplicated initialization: example: I2C Physical Layer could be used for several EVAL Drivers
- Intuitive functionalities based on high level use case
- Portable BSP drivers for different external devices

2.1.3.2 List of BSP drivers

The **BSP drivers** offer a set of APIs relative to the hardware components available in the hardware boards (LEDs, Buttons and COM port).



```

STM32MP15xx_DISCO
├── bumpversion.cfg
├── Release_Notes.html
├── STM32MP15xx_DISCO_BSP_User_Manual.chm
├── stm32mp15xx_disco_bus.c
├── stm32mp15xx_disco_bus.h
├── stm32mp15xx_disco.c
├── stm32mp15xx_disco_conf_template.h
├── stm32mp15xx_disco_errno.h
├── stm32mp15xx_disco.h
├── stm32mp15xx_disco_stpmic1.c
├── stm32mp15xx_disco_stpmic1.h
└── STM32MP15xx_EVAL
    ├── bumpversion.cfg
    ├── Release_Notes.html
    ├── STM32MP15xx_EVAL_BSP_User_Manual.chm
    ├── stm32mp15xx_eval_bus.c
    ├── stm32mp15xx_eval_bus.h
    ├── stm32mp15xx_eval.c
    ├── stm32mp15xx_eval_conf_template.h
    ├── stm32mp15xx_eval_errno.h
    ├── stm32mp15xx_eval.h
    ├── stm32mp15xx_eval_stpmic1.c
    └── stm32mp15xx_eval_stpmic1.h
  
```

2.2 Level 1 (Middlewares)

Middleware components are a set of libraries providing a set of services. **STM32Cube MP1 Package** offers 2 main components : **OpenAMP** and **FreeRTOS**

Each middleware component is mainly composed of:

- Library core: this is the core of a component; it manages the main library state machine and the data flow between the several modules.
- Interface layer: the interface layer is generally used to link the component core with the lower layers like the HAL and the BSP drivers

2.2.1 OpenAMP

OpenAMP is a library implementing the Remote Processor Service framework (RPMsg) which is a messaging mechanism to communicate with a remote processor.

- Load and control Cortex[®]-M firmware
- Inter processor communication

Information

Note:

- Please refer to [Coprocessor_management_overview](#) to get more information related to coprocessor management

2.2.2 FreeRTOS

FreeRTOS is a Free Real Time Operating System (RTOS). The **FreeRTOS** offers preemptive real-time performance with optimized context switch and interrupt times, enabling fast, highly predictable response times.



It includes the following main features :

- Small memory fingerprint
- High portability
- Multithread management
- Pre-emptive scheduling
- Fast interrupt response
- Extensive inter-process communication
- Synchronization facilities
- Tickless operation during low-power mode
- Open source standard
- CMSIS compatibility layer

2.3 Level 2 (Boards demonstrations)

The **Boards demonstrations** level is composed of a single layer which provides all Examples and Applications. It includes also all STM32CubeIDE projects for each supported board as well as Templates source files.

There are 4 kinds of projects demonstrating different usages of software APIs from level 0 (Drivers) and level 1 (Middleware):

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- **Applications projects** showing how to use the middleware components (Level 1) and how to integrate them with the hardware and BSP/HAL layers (Level 0). These applications could be hybrid and use several other middleware components.
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2.4 Utilities

The **Utilities** is a set of common utilities and services offered by **STM32Cube MP1 Package** and is composed of different components :

```
└─ Utilities
  └─ ResourceManager    Services for coprocessing in multi-core devices. Refer to Resource_manager_for_coprocessing
```



2.5 CMSIS

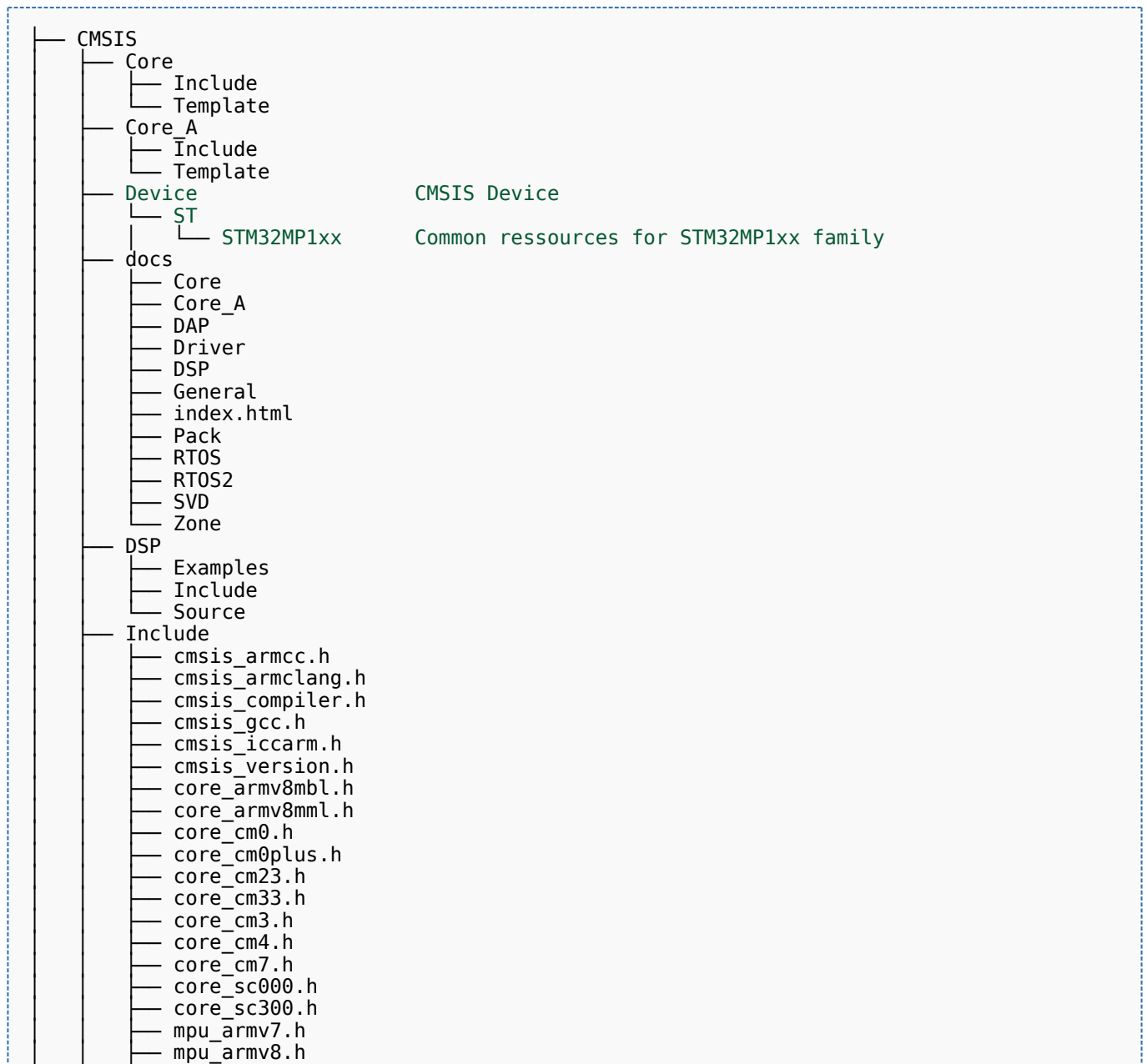
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This vendor part is called **CMSIS Device** and it provides interrupt list, peripherals registers description and associated defines for all registers bit fields.

- **CMSIS** structure overview:





3 STM32Cube MP1 Package versus legacy STM32Cube MCU Package

STM32 MPU devices introduce light differences with STM32 MCU. So please find hereafter a short description of the main differences between **STM32Cube MP1 Package** and **STM32Cube MCU Package**:

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Notes:

- All Middlewares provided by **STM32Cube MCU Package** should be compatible with MPU environment even if not provided in **STM32Cube MP1 Package** (it means they are not tested)
- All BSP components provided by **STM32Cube MCU Package** are not compatible with MPU environment as they are managed by Linux OS on main processor Cortex A
- There is no Flash HAL driver as there is no volatile embedded FLASH dedicated to Cortex-M in MPU devices
- Specific pieces of software have been added to handle multi-core operations:
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 - [Resource Manager](#) library for system resource management
 - Virtual UART driver (specific usage when Linux is used on Cortex-A)
 - Linux script to load **STM32Cube MPU** firmware running on Cortex-M core (specific usage when Linux is used on Cortex-A)

Information

Note:

- Please refer to [Getting_started_with_STM32_MPU_devices](#) article to get an overview of STM32 MPU devices



4 References

Universal Asynchronous Receiver/Transmitter

Universal Synchronous/Asynchronous Receiver/Transmitter