



How to control a GPIO in kernel space



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1 Purpose

This article gives an example of a driver that **controls GPIOs from kernel space**.

Sample source files are provided as examples: **kernel module** (driver), **device tree** and **Makefile**.

This example is available for [STM32MP15_Evaluation_boards](#) or [STM32MP15_Discovery_kits](#)

2 Code

2.1 Objective

Sample gpiolib usage code that makes an LED blink for 20 seconds.

2.2 Device tree

```
dummy_device {  
    compatible = "st,dummy";  
    status = "okay";  
    greenled-gpios = <&gpioa 14 0>;  
};
```

See [GPIO_device_tree_configuration](#) for more details of GPIO use in a device tree.

2.3 Kernel module code

```
#include <linux/module.h>
#include <linux/of_device.h>
#include <linux/kernel.h>
#include <linux/delay.h>
#include <linux/gpio/consumer.h>
#include <linux/platform_device.h>

struct gpio_desc *red, *green;

static int gpio_init_probe(struct platform_device *pdev)
{
    int i = 0;

    printk("GPIO example init\n");

    /* "greenled" label is matching the device tree declaration. OUT_LOW is the value
at init */
    green = devm_gpiod_get(&pdev->dev, "greenled", GPIOD_OUT_LOW);

    /* blink of the green led */
    while (i < 10)
    {
        ssleep(1);
        gpiod_set_value(green, 1);

        ssleep(1);
        gpiod_set_value(green, 0);

        i++;
    }

    return(0);
}

static int gpio_exit_remove(struct platform_device *pdev)
{
    printk("GPIO example exit\n");

    return(0);
}

/* this structure does the matching with the device tree */
/* if it does not match the compatible field of DT, nothing happens */
static struct of_device_id dummy_match[] = {
    {.compatible = "st,dummy"},
    { /* end node */ }
};

static struct platform_driver dummy_driver = {
    .probe = gpio_init_probe,
    .remove = gpio_exit_remove,
    .driver = {
        .name = "dummy_driver",
        .owner = THIS_MODULE,
        .of_match_table = dummy_match,
    }
};

module_platform_driver(dummy_driver);
```



```
MODULE_AUTHOR("Bernard Puel");  
MODULE_DESCRIPTION("Gpio example");  
MODULE_LICENSE("GPL");  
MODULE_ALIAS("platform:dummy_driver");
```

2.4 Kernel module build

See [Adding_external_out-of-tree_Linux_kernel_modules](#) for further information on module compilation.

2.5 Kernel module use

```
PC $> scp dummy_driver.ko root@<board ip address>:/lib/modules/
```

- Update dependency descriptions for loadable kernel modules, and synchronize the data on disk with memory

```
Board $> /sbin/depmod -a  
Board $> sync
```

- Insert the kernel module example into the Linux kernel

```
Board $> modprobe dummy_driver  
[18167.821725] dummy_driver: GPIO example init
```

Light-emitting diode

General-Purpose Input/Output (A realization of open ended transmission between devices on an embedded level. These pins available on a processor can be programmed to be used to either accept input or provide output to external devices depending on user desires and applications requirements.)

Device Tree